

Outlier-aware Dictionary Learning for Sparse Representation

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Sparse Representation

Underdetermined Linear System of Equations

■ $\mathbf{y} = \mathbf{D}\mathbf{x} + \mathbf{e}$

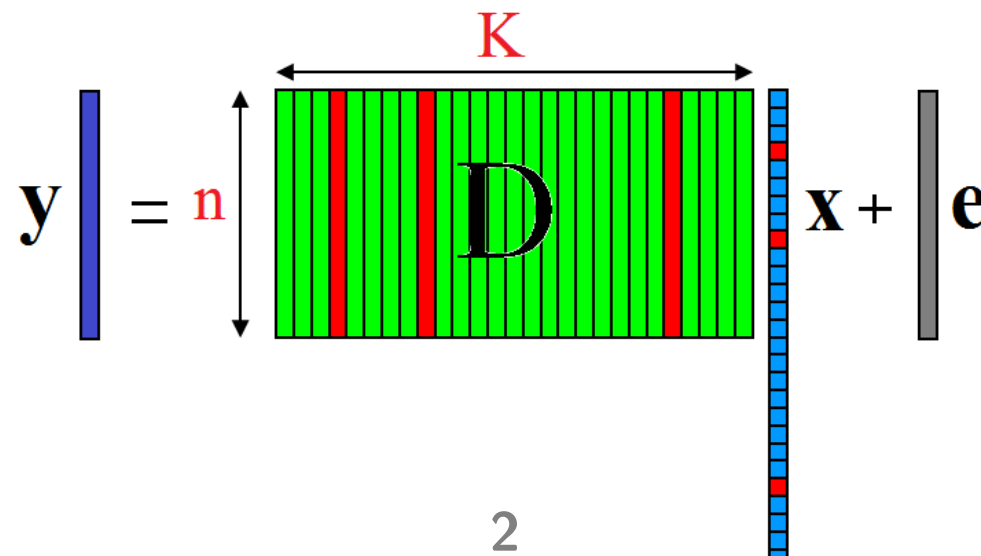
☞ $\mathbf{y} \in \mathbb{R}^n$, $\mathbf{D} \in \mathbb{R}^{n \times K}$, $\mathbf{x} \in \mathbb{R}^K$, $\mathbf{e} \in \mathbb{R}^n$

☞ $\mathbf{D} = [\mathbf{d}_1 \ \mathbf{d}_2 \ \dots \ \mathbf{d}_K]$: dictionary, \mathbf{d}_i : atom

☞ The dictionary is usually overcomplete: $K > n$

■ Sparse representation problem:

$$\mathbf{x}^* = \underset{\mathbf{x}}{\operatorname{argmin}} \|\mathbf{x}\|_0 \quad \text{subject to} \quad \|\mathbf{y} - \mathbf{D}\mathbf{x}\|_2 \leq \epsilon$$



Choosing the Dictionary

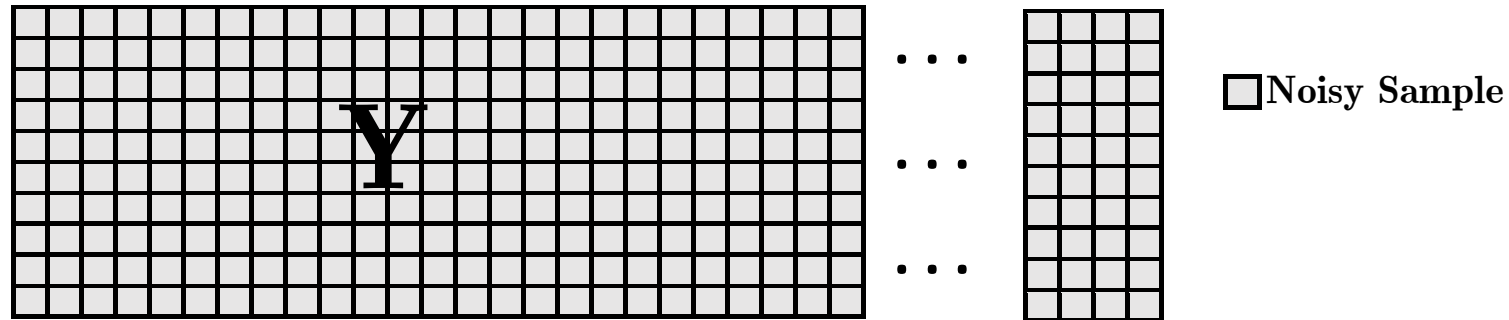
■ Pre-defined and fixed dictionaries: Fourier, Gabor, DCT, wavelet, ...

- ✓ Fast computations
- ✗ Unable to sparsely represent a given signal class

■ Learned dictionaries

- ✓ More efficient for sparse representation
- ✓ Very promising results in many applications: image enhancement, pattern recognition, ...
- ✗ High computational load

Dictionary Learning (DL)



- Given a noisy training data matrix, $\mathbf{Y} = [\mathbf{y}_1, \dots, \mathbf{y}_L]$, the goal is to find an over-complete set of basis functions (atoms) over which each data can be sparsely represented

Training Data Model

$$\mathbf{y}_i = \mathbf{D}\mathbf{x}_i + \mathbf{n}_i \quad i = 1, \dots, L$$

👉 $p(\mathbf{x}) \propto \exp\left(-\frac{\|\mathbf{x}\|_1}{\beta_1}\right)$

👉 $p(\mathbf{n}) \propto \exp\left(-\frac{\|\mathbf{n}\|_2^2}{\beta_2}\right)$

Dictionary Learning (DL)

MAP Estimation of Dictionary and Representations

$$\min_{\mathbf{D}, \{\mathbf{x}_i\}_{i=1}^L} \sum_i \|\mathbf{y}_i - \mathbf{D}\mathbf{x}_i\|_2^2 \quad \text{subject to} \quad \begin{cases} \|\mathbf{d}_i\|_2 = 1, & i = 1, \dots, K \\ \|\mathbf{x}_j\|_0 \leq T_0, & j = 1, \dots, L \end{cases}$$

■ $\|\mathbf{x}\|_0 \triangleq |\text{supp}(\mathbf{x}) = \{i : x_i \neq 0\}|$

Solution to the Dictionary Learning Problem

- **Alternating Minimization** Starting with an initial dictionary, the following two stages are repeated several times:

1 Sparse representation:

$$\mathbf{X}^{(k+1)} = \operatorname{argmin}_{\mathbf{X} \in \mathcal{X}} \|\mathbf{Y} - \mathbf{D}^{(k)}\mathbf{X}\|_F^2 \quad \text{subject to} \quad \|\mathbf{x}_j\|_0 \leq T_0, \quad j = 1, \dots, L \implies \text{OMP}$$

2 Dictionary update:

$$\mathbf{D}^{(k+1)} = \operatorname{argmin}_{\mathbf{D} \in \mathcal{D}} \|\mathbf{Y} - \mathbf{D}\mathbf{X}^{(k+1)}\|_F^2 \quad \text{subject to} \quad \|\mathbf{d}_i\|_2 = 1, \quad i = 1, \dots, K \implies \text{Differentiating}$$

Image Denoising Using Dictionary Learning

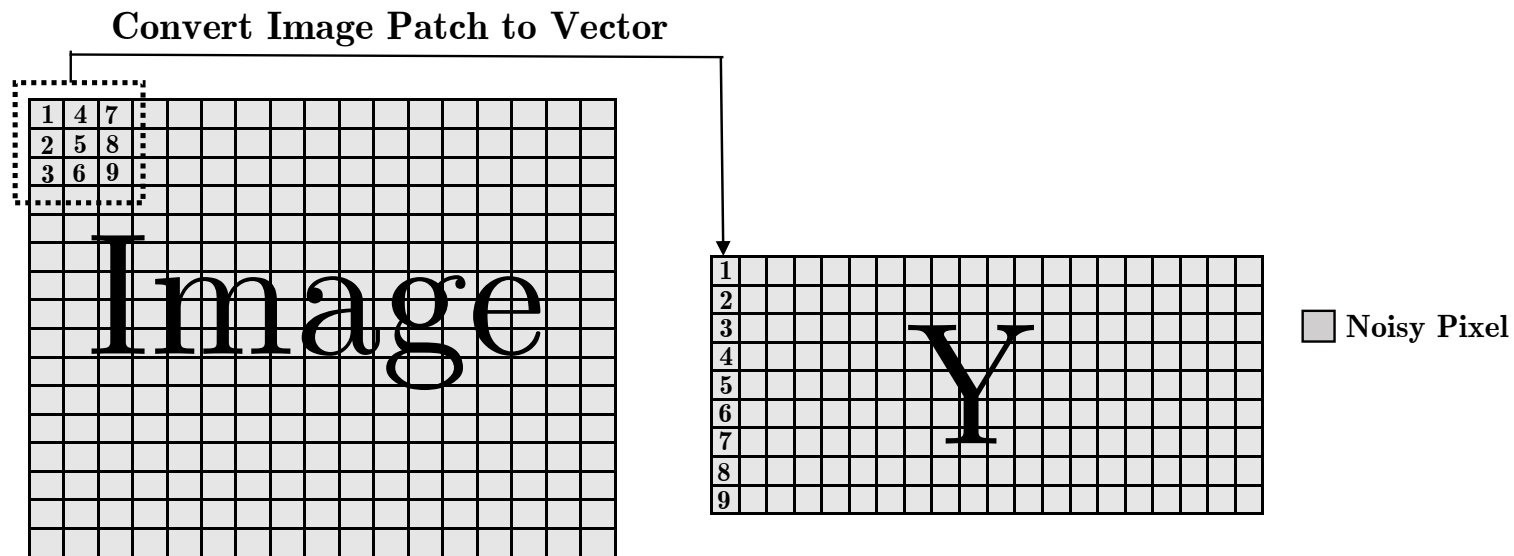
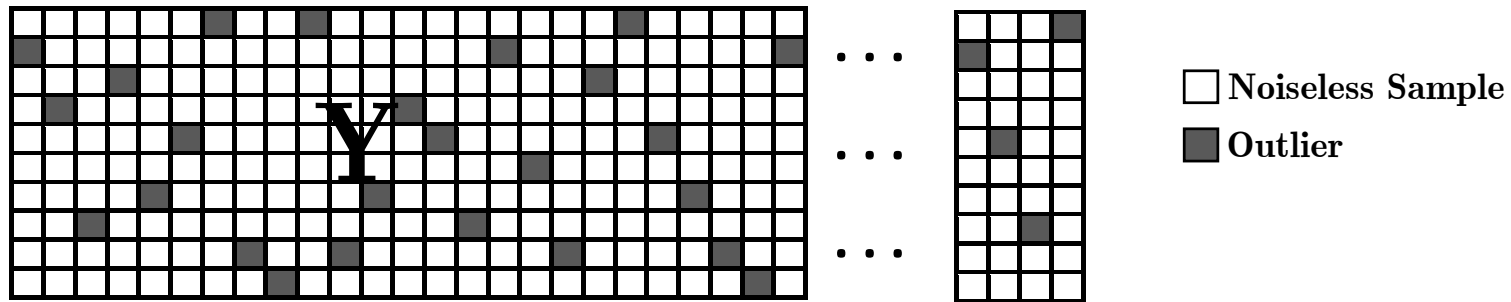


Image Denoising

- Training Image Dictionary (\mathbf{D}^*)
- Estimating Denoised Image Patch Representation
 - 👉 $\hat{\mathbf{x}} = \text{OMP}_{\mathbf{D}^*}(\mathbf{y})$
- Reconstructing Denoised Image Patch
 - 👉 $\hat{\mathbf{y}} = \mathbf{D}^* \hat{\mathbf{x}}$

Robust Dictionary Learning



Problem Formulation

■ Training Data Model:

$$\mathbf{y}_i = \mathbf{D}\mathbf{x}_i + \mathbf{n}_i \quad i = 1, \dots, L$$

☞ $p(\mathbf{x}) \propto \exp\left(-\frac{\|\mathbf{x}\|_1}{\beta_1}\right)$

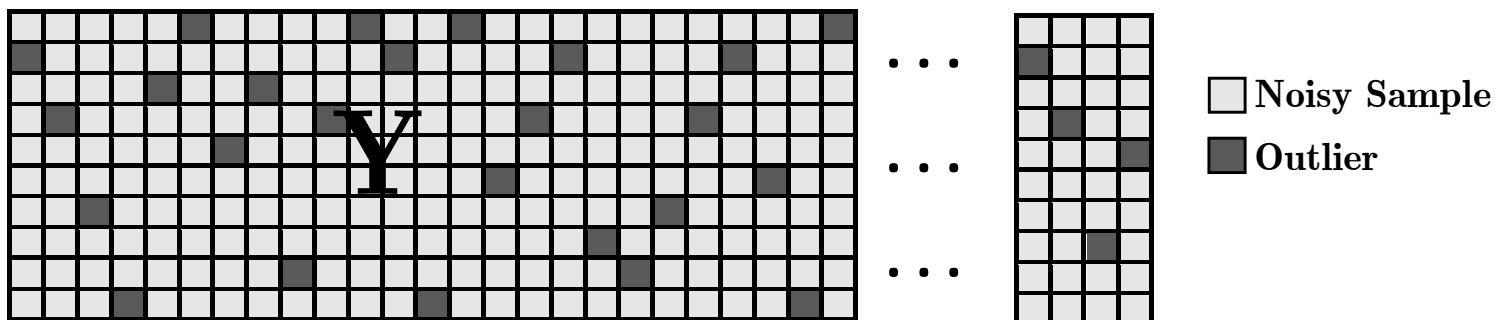
☞ $p(\mathbf{n}) \propto \exp\left(-\frac{\|\mathbf{n}\|_1}{\beta_2}\right)$

■ MAP Estimation of Dictionary and Representations

$$\min_{\mathbf{D}, \{\mathbf{x}_i\}_{i=1}^L} \sum_i (\|\mathbf{y}_i - \mathbf{D}\mathbf{x}_i\|_1 + \lambda \|\mathbf{x}_i\|_1) \quad \text{subject to} \quad \|\mathbf{d}_i\|_2 = 1, \quad i = 1, \dots, K$$

☞ Strategy to Solve \Rightarrow $\begin{cases} \text{w.r.t. } \mathbf{D} \Rightarrow \text{Iteratively Reweighted Least Squares} \\ \text{w.r.t. } \{\mathbf{x}_i\}_{i=1}^L \Rightarrow \text{Iteratively Reweighted Least Squares} \end{cases}$

Robust Dictionary Learning by Error Source Decomposition



Problem Formulation

■ Training Data Model:

$$\mathbf{y}_i = \mathbf{D}\mathbf{x}_i + \mathbf{n}_i + \mathbf{o}_i \quad i = 1, \dots, L$$

$$\text{👉 } p(\mathbf{x}) \propto \exp\left(-\frac{\|\mathbf{x}\|_1}{\beta_1}\right)$$

$$\text{👉 } p(\mathbf{n}) \propto \exp\left(-\frac{\|\mathbf{n}\|_2^2}{\beta_2}\right)$$

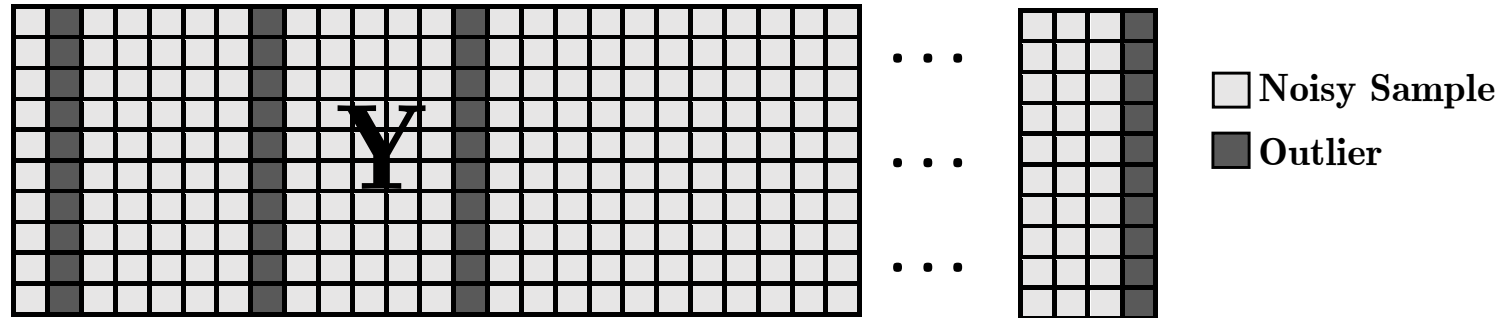
$$\text{👉 } p(\mathbf{o}) \propto \exp\left(-\frac{\|\mathbf{o}\|_1}{\beta_3}\right)$$

■ MAP Estimation of Dictionary and Representations

$$\min_{\mathbf{D}, \{\mathbf{x}_i\}_{i=1}^L, \{\mathbf{o}_i\}_{i=1}^L} \sum_i (\|\mathbf{y}_i - \mathbf{D}\mathbf{x}_i - \mathbf{o}_i\|_2^2 + \lambda \|\mathbf{o}_i\|_1) \quad \text{subject to} \quad \begin{cases} \|\mathbf{d}_i\|_2 = 1, \quad i = 1, \dots, K \\ \|\mathbf{x}_j\|_0 \leq T_0, \quad j = 1, \dots, L \end{cases}$$

$$\text{👉 Strategy to Solve} \quad \Rightarrow \quad \begin{cases} \text{w.r.t. } \mathbf{D} \Rightarrow \text{Differentiating} \\ \text{w.r.t. } \{\mathbf{x}_i\}_{i=1}^L, \{\mathbf{o}_i\}_{i=1}^L \Rightarrow \text{Shrinkage} \end{cases}$$

Outlier Aware Dictionary Learning (Proposed)



Problem Formulation

■ Training Data Model:

$$\mathbf{y}_i = \mathbf{D}\mathbf{x}_i + \mathbf{n}_i + \mathbf{o}_i \quad i = 1, \dots, L$$

$$\text{👉 } p(\mathbf{x}) \propto \exp\left(-\frac{\|\mathbf{x}\|_1}{\beta_1}\right)$$

$$\text{👉 } p(\mathbf{n}) \propto \exp\left(-\frac{\|\mathbf{n}\|_2^2}{\beta_2}\right)$$

$$\text{👉 } p(\mathbf{o}) \propto \exp\left(-\frac{\|\mathbf{o}\|_2}{\beta_3}\right)$$

■ MAP Estimation of Dictionary and Representations

$$\min_{\mathbf{D}, \{\mathbf{x}_i\}_{i=1}^L, \{\mathbf{o}_i\}_{i=1}^L} \sum_i (\|\mathbf{y}_i - \mathbf{D}\mathbf{x}_i - \mathbf{o}_i\|_2^2 + \lambda \|\mathbf{o}_i\|_2) \quad \text{subject to} \quad \begin{cases} \|\mathbf{d}_i\|_2 = 1, \quad i = 1, \dots, K \\ \|\mathbf{x}_j\|_0 \leq T_0, \quad j = 1, \dots, L \end{cases}$$

$$\min_{\mathbf{D}, \mathbf{X}, \mathbf{O}} \|\mathbf{Y} - \mathbf{D}\mathbf{X} - \mathbf{O}\|_F^2 + \lambda \|\mathbf{O}\|_{21} \quad \text{subject to} \quad \begin{cases} \|\mathbf{d}_i\|_2 = 1, \quad i = 1, \dots, K \\ \|\mathbf{x}_j\|_0 \leq T_0, \quad j = 1, \dots, L \end{cases}$$

Outlier Aware Dictionary Learning (Proposed)

Solution Strategy

■ Alternating Minimization:

👉 w.r.t. $\{\mathbf{x}_i\}_{i=1}^L \Rightarrow \mathbf{x}_i = \text{OMP}_{\mathbf{D}}(\mathbf{y}_i - \mathbf{o}_i), i = 1, \dots, L$

👉 w.r.t. $\{\mathbf{o}_i\}_{i=1}^L \Rightarrow \mathbf{o}_i = \begin{cases} (1 - \frac{\lambda}{2\|\mathbf{r}_i\|_2})\mathbf{r}_i, & \text{if } \|\mathbf{r}_i\|_2 > \frac{\lambda}{2} \\ \mathbf{0}, & \text{otherwise} \end{cases} \quad \mathbf{r}_i = \mathbf{y}_i - \mathbf{D}\mathbf{x}_i, i = 1, \dots, L$

👉 w.r.t. $\mathbf{D} \Rightarrow \mathbf{D} = (\mathbf{Y} - \mathbf{O})\mathbf{X}^T(\mathbf{X}\mathbf{X}^T)^{-1}$

■ Initialization

👉 $\mathbf{D} \Rightarrow$ Overcomplete DCT

👉 $\{\mathbf{o}_i\}_{i=1}^L \Rightarrow \mathbf{o}_i = \mathbf{0}, i = 1, \dots, L$

- At the beginning, all training signal are considered not to be an outlier.

Image Denoising Based on OADL

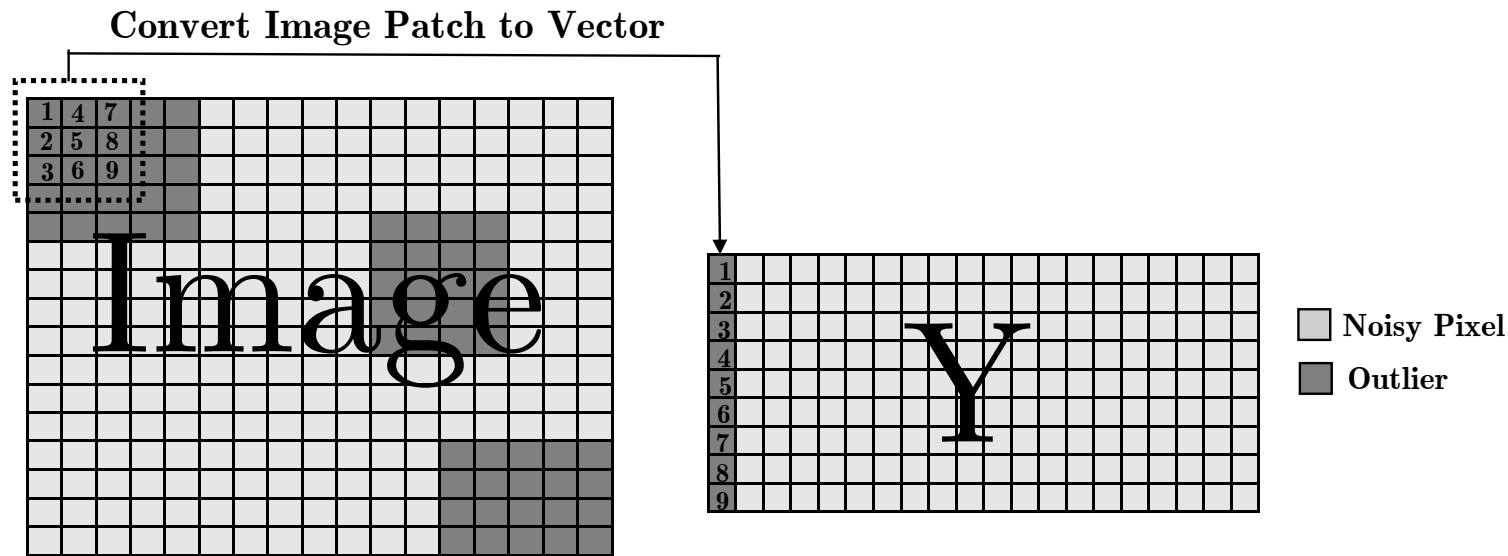


Image Denoising

- Training Image Dictionary Using OADL(\mathbf{D}^*)

- Estimating Denoised Image Patch Representation

👉 $(\hat{\mathbf{x}}, \hat{\mathbf{o}}) = \text{Alternating Minimization} \begin{cases} \min_{\mathbf{x}} \|\mathbf{x}\|_0 & \text{subject to } \|(\mathbf{y} - \mathbf{o}) - \mathbf{D}\mathbf{x}\|_2 \leq \epsilon \\ \min_{\mathbf{o}} \|(\mathbf{y} - \mathbf{D}\mathbf{x}) - \mathbf{o}\|_2^2 + \|\mathbf{o}\|_2 \end{cases}$

- Reconstructing Denoised Image Patch

👉 $\hat{\mathbf{y}} = \mathbf{D}^* \hat{\mathbf{x}}$

Simulation Results

■ Synthetic Data

- Generate a random dictionary (\mathbf{D})
- Generate 2500 training signals and 500 test signals using 3 atoms of \mathbf{D}
- Add Gaussian noise ($\mathcal{N}(\mathbf{0}, 0.01^2\mathbf{I})$) to each of training signals
- Add Gaussian noise ($\mathcal{N}(\mathbf{0}, 0.04^2\mathbf{I})$) to $p\%$ of randomly selected training signals (outlier)
- Train a dictionary using training signals (\mathbf{D}^*)
- Evaluate the ability of dictionary to code test signals using 3 atoms of \mathbf{D}^*

■ Image Denoising

- Select 6 benchmark images (256×256)
- Add Gaussian noise ($\mathcal{N}(0, 10^2)$) to each of image pixels
- Add Gaussian noise ($\mathcal{N}(0, 20^2)$) to B blocks of pixels according to the following pattern
- Denoise the resultant image

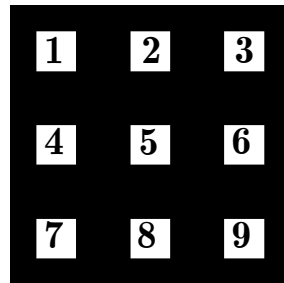
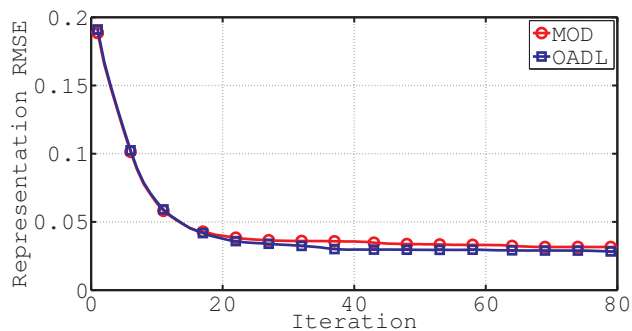
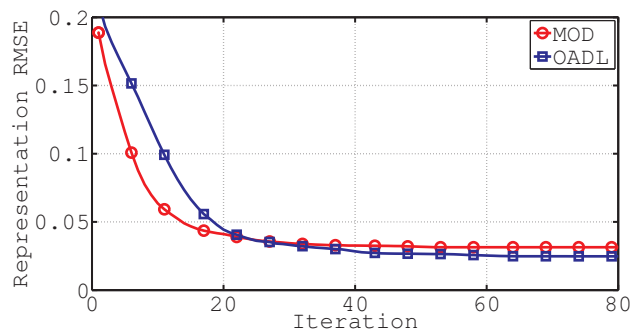


Figure: Outlier block pattern

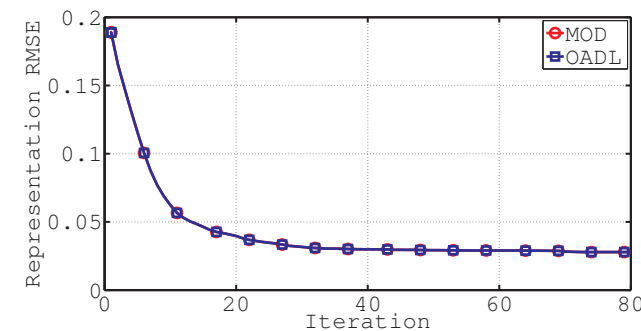
Simulation Results - Synthetic Data



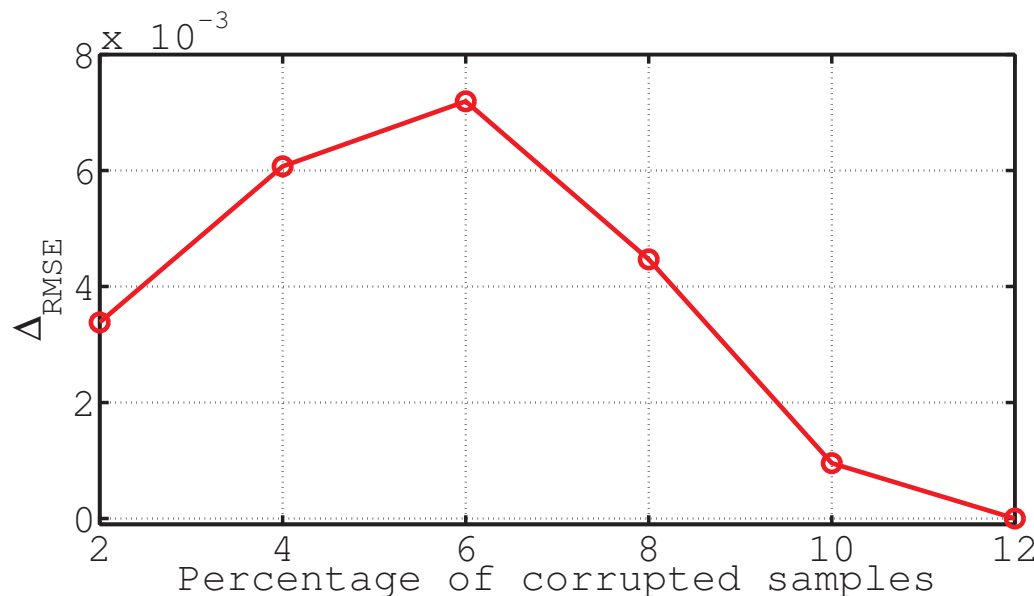
(a) $p = 2\%$



(b) $p = 6\%$



(c) $p = 12\%$



(d) Final RMSE difference

Figure: (a)-(c) Test data representation RMSE along iterations for $p = 2, 4$ and 6 , respectively. (d) Final representation RMSE of test data versus p

Simulation Results - Synthetic Data

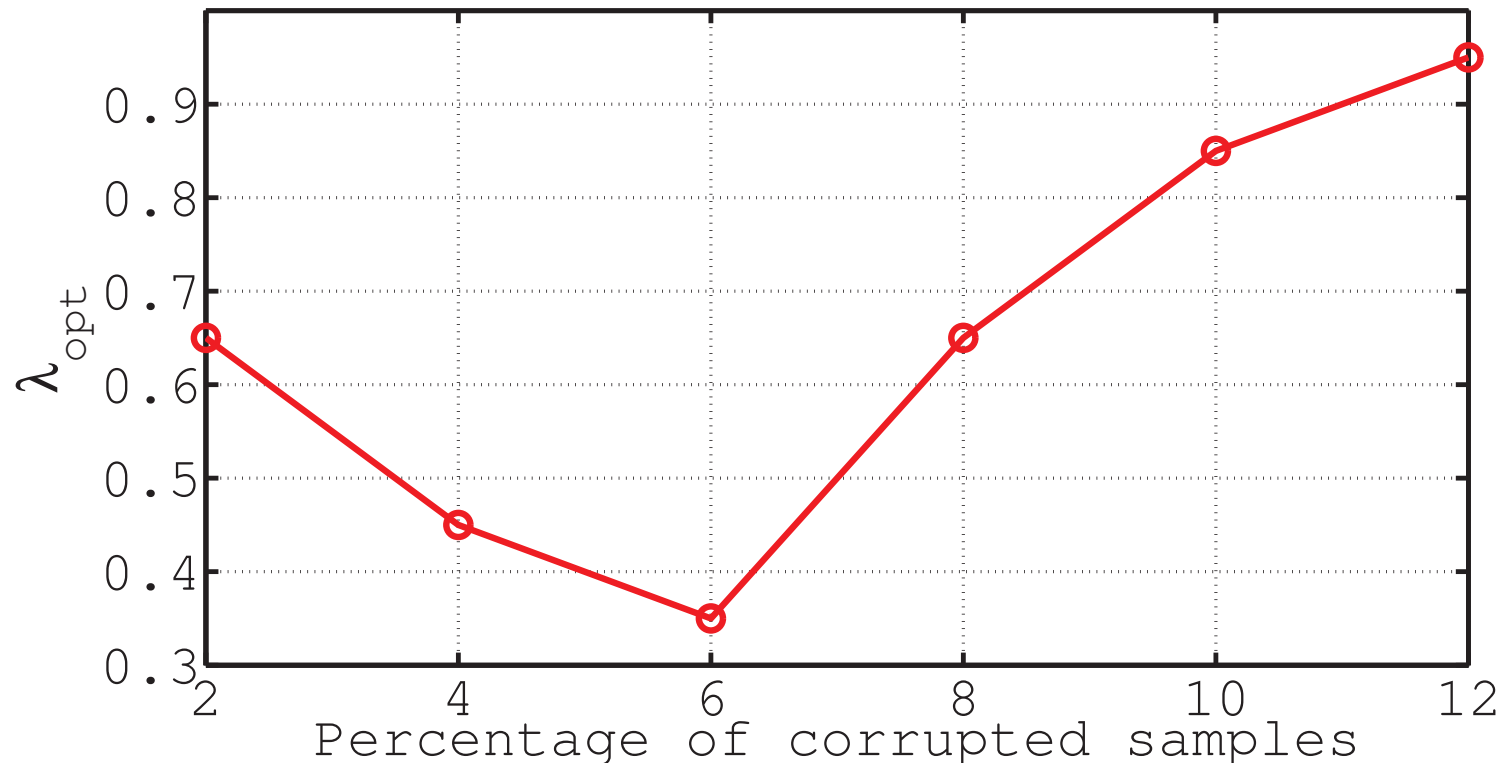


Figure: Best λ , which minimizes test data representation RMSE, versus percentage of outliers.

- $p = 2\%$ to 6% $\left\{ \begin{array}{l} p \text{ directly related to } \beta_3 \\ \lambda \text{ inversely related to } \beta_3 \end{array} \right. \Rightarrow p \text{ inversely related to } \lambda$
- $p = 6\%$ to 12% $\left\{ \begin{array}{l} \text{Violation of outlier sparsity assumption} \\ \text{OADL approaches regular Dictionary Learning} \end{array} \right. \Rightarrow p \text{ directly related to } \lambda$

Simulation Results - Image Denoising

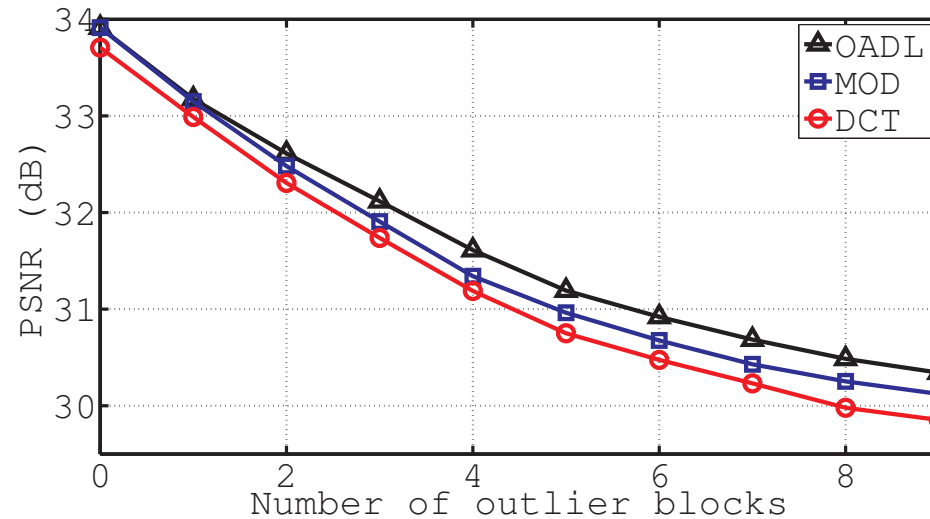


Figure: Averaged PSNR over 6 different test images versus number of outlier blocks.

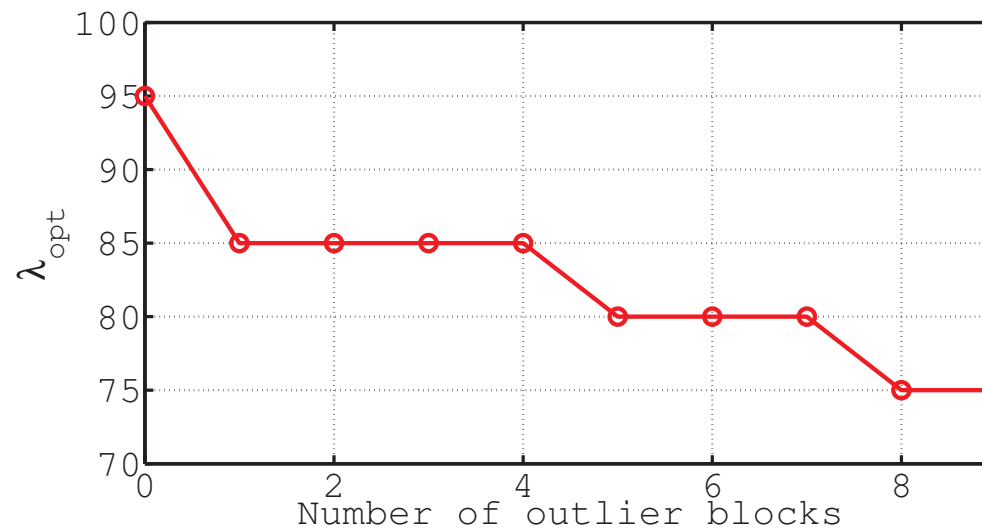


Figure: Best λ , which maximizes PSNR, versus percentage of outliers.

Conclusions

- A new and practical placement of outlier was considered.
- We introduce a new model for training signals based on separating noise and outlier source.
- We formulate DL problem using MAP estimation.
- We introduce a fast and efficient algorithm to solve the proposed robust dictionary learning problem.
- Simulation results showed that our new method leads to considerable improvements over traditional methods

References

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