

1 Gradient, Divergence, Curl, and Laplacian

1.1 Cartesian Coordinates (x, y, z)

$$\nabla V = \frac{\partial V}{\partial x} \hat{a}_x + \frac{\partial V}{\partial y} \hat{a}_y + \frac{\partial V}{\partial z} \hat{a}_z \quad (1)$$

$$\nabla \cdot \vec{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z} \quad (2)$$

$$\nabla \times \vec{A} = \begin{vmatrix} \hat{a}_x & \hat{a}_y & \hat{a}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_x & A_y & A_z \end{vmatrix} \quad (3)$$

$$\nabla^2 V = \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2} \quad (4)$$

1.2 Cylindrical Coordinates (ρ, ϕ, z)

$$\nabla V = \frac{\partial V}{\partial \rho} \hat{a}_\rho + \frac{1}{\rho} \frac{\partial V}{\partial \phi} \hat{a}_\phi + \frac{\partial V}{\partial z} \hat{a}_z \quad (5)$$

$$\nabla \cdot \vec{A} = \frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho A_\rho) + \frac{1}{\rho} \frac{\partial A_\phi}{\partial \phi} + \frac{\partial A_z}{\partial z} \quad (6)$$

$$\nabla \times \vec{A} = \frac{1}{\rho} \begin{vmatrix} \hat{a}_\rho & \rho \hat{a}_\phi & \hat{a}_z \\ \frac{\partial}{\partial \rho} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} \\ A_\rho & \rho A_\phi & A_z \end{vmatrix} \quad (7)$$

$$\nabla^2 V = \frac{1}{\rho} \frac{\partial}{\partial \rho} \left(\rho \frac{\partial V}{\partial \rho} \right) + \frac{1}{\rho^2} \frac{\partial^2 V}{\partial \phi^2} + \frac{\partial^2 V}{\partial z^2} \quad (8)$$

1.3 Spherical Coordinates (r, θ, ϕ)

$$\nabla V = \frac{\partial V}{\partial r} \hat{a}_r + \frac{1}{r} \frac{\partial V}{\partial \theta} \hat{a}_\theta + \frac{1}{r \sin \theta} \frac{\partial V}{\partial \phi} \hat{a}_\phi \quad (9)$$

$$\nabla \cdot \vec{A} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 A_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta A_\theta) + \frac{1}{r \sin \theta} \frac{\partial A_\phi}{\partial \phi} \quad (10)$$

$$\nabla \times \vec{A} = \frac{1}{r^2 \sin \theta} \begin{vmatrix} \hat{a}_r & r \hat{a}_\theta & r \sin \theta \hat{a}_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ A_r & r A_\theta & r \sin \theta A_\phi \end{vmatrix} \quad (11)$$

$$\nabla^2 V = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial V}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial V}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 V}{\partial \phi^2} \quad (12)$$

2 Useful Vector Identities

$$\vec{A} \cdot (\vec{B} \times \vec{C}) = \vec{B} \cdot (\vec{C} \times \vec{A}) = \vec{C} \cdot (\vec{A} \times \vec{B}) \quad (13)$$

$$\vec{A} \times (\vec{B} \times \vec{C}) = \vec{B}(\vec{A} \cdot \vec{C}) - \vec{C}(\vec{A} \cdot \vec{B}) \quad (14)$$

$$(\vec{A} \times \vec{B}) \cdot (\vec{C} \times \vec{D}) = (\vec{A} \cdot \vec{C})(\vec{B} \cdot \vec{D}) - (\vec{A} \cdot \vec{D})(\vec{B} \cdot \vec{C}) \quad (15)$$

$$\nabla(\psi V) = \psi \nabla V + V \nabla \psi \quad (16)$$

$$\nabla \cdot (\psi \vec{A}) = \nabla \psi \cdot \vec{A} + \psi \nabla \cdot \vec{A} \quad (17)$$

$$\nabla \times (\psi \vec{A}) = \nabla \psi \times \vec{A} + \psi \nabla \times \vec{A} \quad (18)$$

$$\nabla \cdot (\vec{A} \times \vec{B}) = \vec{B} \cdot (\nabla \times \vec{A}) - \vec{A} \cdot (\nabla \times \vec{B}) \quad (19)$$

$$\nabla \times (\vec{A} \times \vec{B}) = \vec{A}(\nabla \cdot \vec{B}) - \vec{B}(\nabla \cdot \vec{A}) + (\vec{B} \cdot \nabla)\vec{A} - (\vec{A} \cdot \nabla)\vec{B} \quad (20)$$

$$\nabla(\vec{A} \cdot \vec{B}) = (\vec{A} \cdot \nabla)\vec{B} + (\vec{B} \cdot \nabla)\vec{A} + \vec{A} \times (\nabla \times \vec{B}) + \vec{B} \times (\nabla \times \vec{A}) \quad (21)$$

$$\nabla \times \nabla V = 0 \quad (22)$$

$$\nabla \cdot (\nabla \times \vec{A}) = 0 \quad (23)$$

$$\nabla \times \nabla \times \vec{A} = \nabla(\nabla \cdot \vec{A}) - \nabla^2 \vec{A} \quad (24)$$

$$\iiint_V \nabla \cdot \vec{A} \, dv = \oiint_S \vec{A} \cdot \vec{ds} \quad (25)$$

$$\iint_S \nabla \times \vec{A} \cdot \vec{ds} = \oint_C \vec{A} \cdot \vec{dl} \quad (26)$$

$$\oiint_S \vec{A} \times \vec{ds} = - \iiint_V \nabla \times \vec{A} \, dv \quad (27)$$

$$\oiint_S \psi \vec{ds} = \iiint_V \nabla \psi \, dv \quad (28)$$

$$\oint_C \psi \vec{dl} = - \iint_S \nabla \psi \times \vec{ds} \quad (29)$$

$$\oiint_S \Phi \nabla \Psi \cdot \vec{ds} = \iiint_V (\nabla \Phi \cdot \nabla \Psi + \Phi \nabla^2 \Psi) \, dv \quad (30)$$

$$\iiint_V (\Phi \nabla^2 \Psi - \Psi \nabla^2 \Phi) \, dv = \oiint_S (\Phi \nabla \Psi - \Psi \nabla \Phi) \cdot \vec{ds} \quad (31)$$

$$\iiint_V (\nabla \times \vec{A} \cdot \nabla \times \vec{B} - \vec{A} \cdot \nabla \times \nabla \times \vec{B}) \, dv = \oiint_S (\vec{A} \times \nabla \times \vec{B}) \cdot \vec{ds} \quad (32)$$

$$\iiint_V (\vec{B} \cdot \nabla \times \nabla \times \vec{A} - \vec{A} \cdot \nabla \times \nabla \times \vec{B}) \, dv = \oiint_S (\vec{A} \times \nabla \times \vec{B} - \vec{B} \times \nabla \times \vec{A}) \cdot \vec{ds} \quad (33)$$

$$\nabla \frac{1}{|\vec{r} - \vec{r}'|} = - \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \quad \nabla \cdot \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} = 4\pi \delta(\vec{r} - \vec{r}') \quad (34)$$

$$\frac{d\vec{A}}{dt} = \frac{\partial \vec{A}}{\partial t} + \vec{A} \nabla \cdot \vec{v} - \nabla \times (\vec{A} \times \vec{v}) \quad \vec{v} = \frac{d\vec{r}}{dt} = \text{velocity} \quad (35)$$

$$\nabla^2(\psi V) = \psi \nabla^2 V + V \nabla^2 \psi + 2 \nabla V \cdot \nabla \psi \quad (36)$$

The Taylor series expansion of a function $\psi(\vec{r})$ is:

$$\psi(\vec{r} + \vec{h}) = \psi(\vec{r}) + (\vec{h} \cdot \nabla)\psi(\vec{r}) + \frac{1}{2!}(\vec{h} \cdot \nabla)^2\psi(\vec{r}) + \dots + \frac{1}{n!}(\vec{h} \cdot \nabla)^n\psi(\vec{r}) + \dots \quad (37)$$

$$f(x+h) = f(x) + h \frac{d}{dx}f(x) + \frac{h^2}{2!} \frac{d^2}{dx^2}f(x) + \dots + \frac{h^n}{n!} \frac{d^n}{dx^n}f(x) + \dots \quad (38)$$