# CS162
# Operating Systems and Systems Programming
# Lecture 21

## Distributed Decision Making, TCP/IP and Sockets

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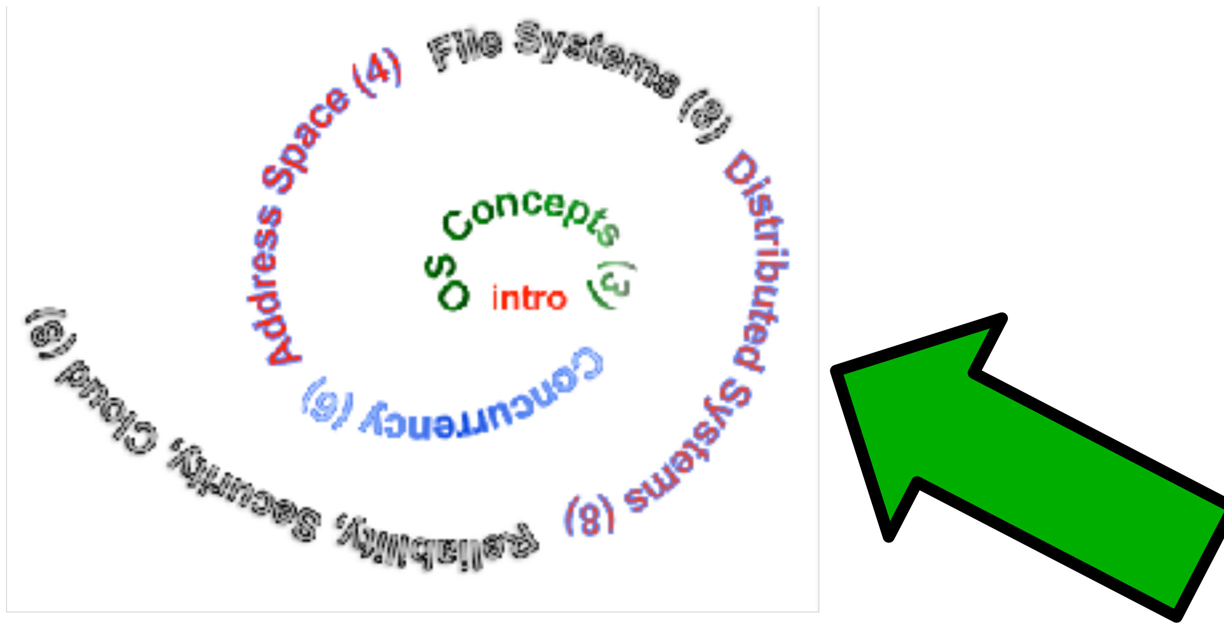
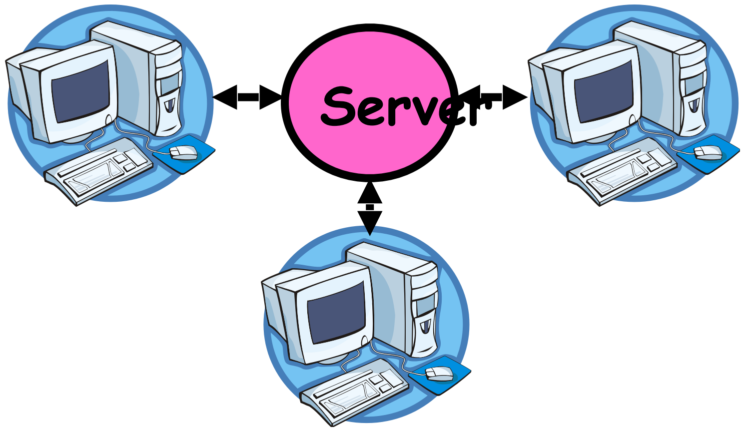
*Acknowledgments: Lecture slides are from the Operating Systems course taught by John Kubiatowicz at* Berkeley, with few minor updates/changes. *When slides are obtained from other sources, a  a reference will be noted on the bottom of that slide, in which case a full list of references is provided on the last slide.*

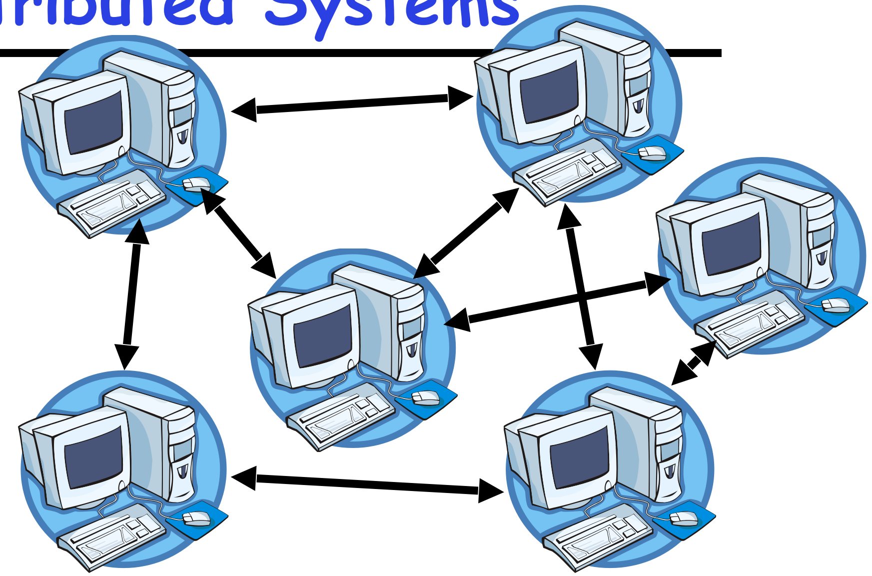
# Next Objective



# Centralized vs Distributed Systems




Client/Server Model



Peer-to-Peer Model

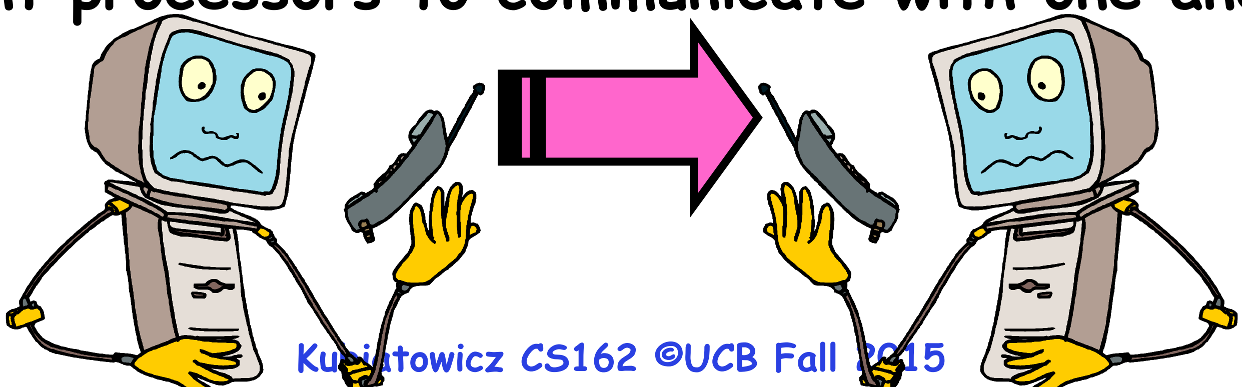
- **Centralized System:** System in which major functions are performed by a single physical computer
  - Originally, everything on single computer
  - Later: client/server model
- **Distributed System:** physically separate computers working together on some task
  - Early model: multiple servers working together
    - » Probably in the same room or building
    - » Often called a "cluster"
  - Later models: peer-to-peer/wide-spread collaboration

# Distributed Systems: Motivation/Issues

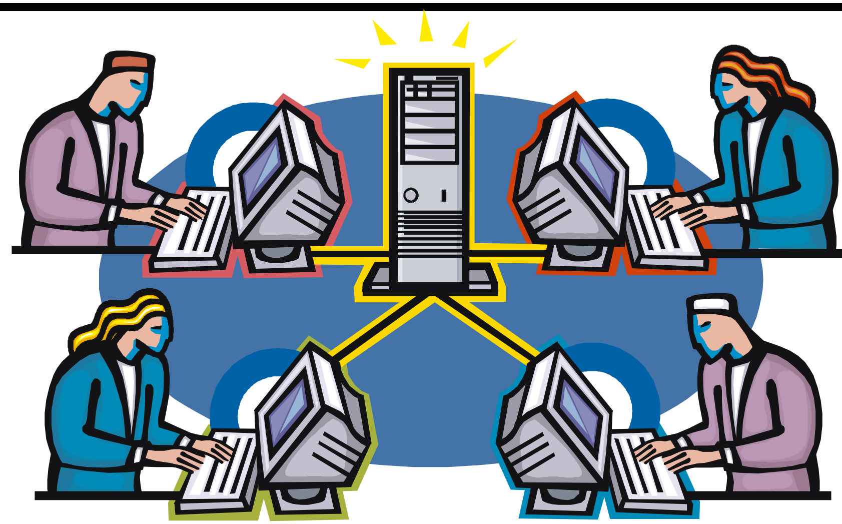
- Why do we want distributed systems?
  - Cheaper and easier to build lots of simple computers
  - Easier to add power incrementally
  - Users can have complete control over some components
  - Collaboration: Much easier for users to collaborate through network resources (such as network file systems)
- The promise of distributed systems:
  - Higher availability: one machine goes down, use another
  - Better durability: store data in multiple locations
  - More security: each piece easier to make secure
- Reality has been disappointing
  - Worse availability: depend on every machine being up
    - » Lamport: "a distributed system is one where I can't do work because some machine I've never heard of isn't working!"
  - Worse reliability: can lose data if any machine crashes
  - Worse security: anyone in world can break into system
- Coordination is more difficult
  - Must coordinate multiple copies of shared state information (using only a network)
  - What would be easy in a centralized system becomes a lot more difficult

# Recall: Distributed Systems: Goals/Requirements

- **Transparency:** the ability of the system to mask its complexity behind a simple interface
- Possible transparencies:
  - **Location:** Can't tell where resources are located
  - **Migration:** Resources may move without the user knowing
  - **Replication:** Can't tell how many copies of resource exist
  - **Concurrency:** Can't tell how many users there are
  - **Parallelism:** System may speed up large jobs by spliting them into smaller pieces
  - **Fault Tolerance**: System may hide varoius things that go wrong in the system
- Transparency and collaboration require some way for different processors to communicate with one another



# Networking Definitions

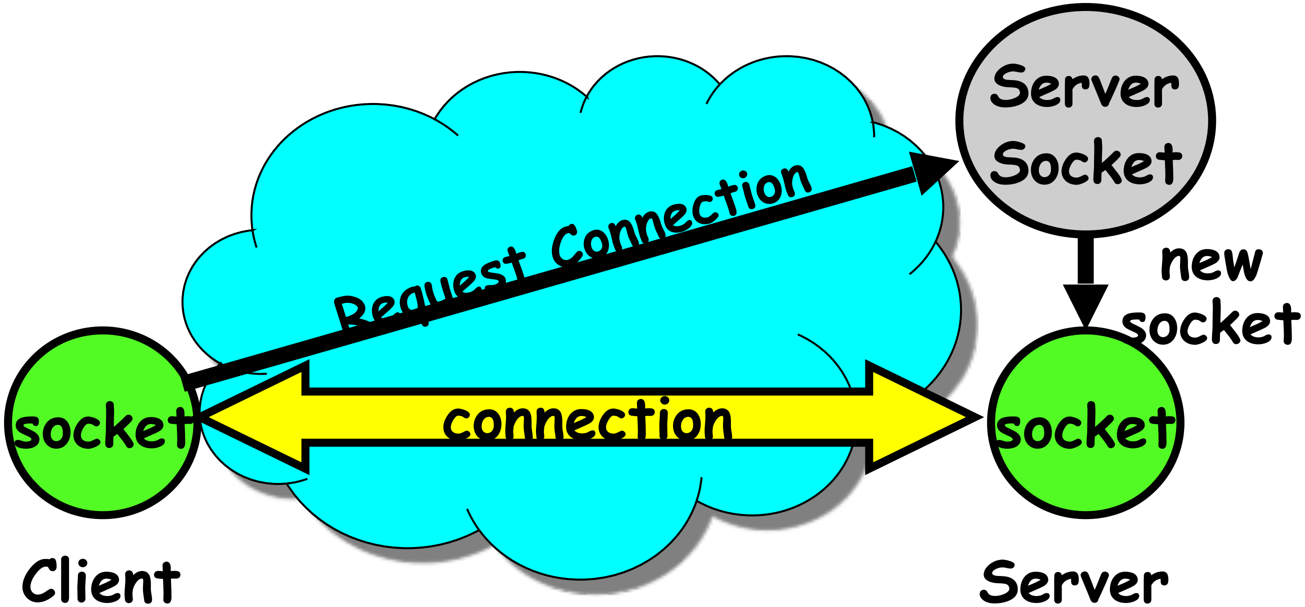


- **Network:** physical connection that allows two computers to communicate
- **Packet:** unit of transfer, sequence of bits carried over the network
  - Network carries packets from one CPU to another
  - Destination gets interrupt when packet arrives
- **Protocol:** agreement between two parties as to how information is to be transmitted

# Recall: Use of TCP: Sockets

- **Socket:** an abstraction of a network I/O queue
  - Embodies one side of a communication channel
    - » Same interface regardless of location of other end
    - » Could be local machine (called "UNIX socket") or remote machine (called "network socket")
  - First introduced in 4.2 BSD UNIX: big innovation at time
    - » Now most operating systems provide some notion of socket
- Using Sockets for Client-Server (C/C++ interface):
  - On server: set up "server-socket"
    - » Create socket, Bind to protocol (TCP), local address, port
    - » Call listen(): tells server socket to accept incoming requests
    - » Perform multiple accept() calls on socket to accept incoming connection request
    - » Each successful accept() returns a new socket for a new connection; can pass this off to handler thread
  - On client:
    - » Create socket, Bind to protocol (TCP), remote address, port
    - » Perform connect() on socket to make connection
    - » If connect() successful, have socket connected to server

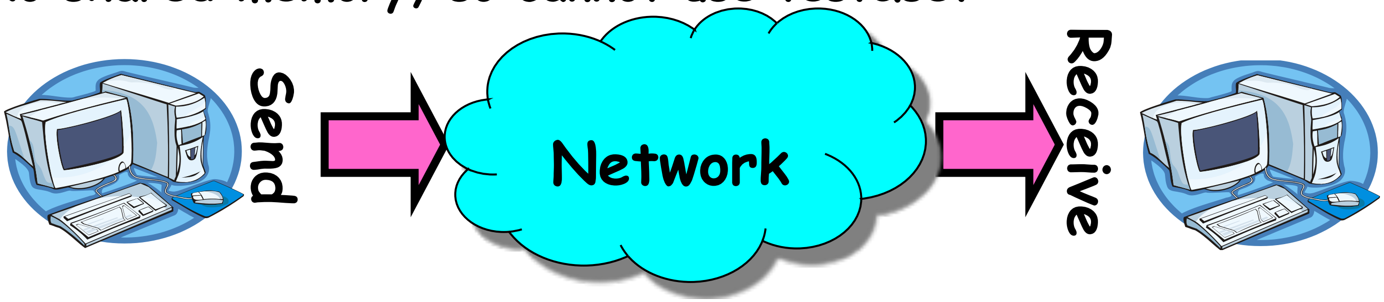
# Recall: Socket Setup over TCP/IP




- Server Socket: Listens for new connections
  - Produces new sockets for each unique connection
- Things to remember:
  - Connection involves 5 values:
    [ Client Addr, Client Port, Server Addr, Server Port, Protocol ]
  - Often, Client Port "randomly" assigned
    » Done by OS during client socket setup
  - Server Port often "well known"
    » 80 (web), 443 (secure web), 25 (sendmail), etc
    » Well-known ports from 0—1023

# Distributed Applications

- How do you actually program a distributed application?
  - Need to synchronize multiple threads, running on different machines
    - » No shared memory, so cannot use test&set




  - One Abstraction: send/receive messages
    - » Already atomic: no receiver gets portion of a message and two receivers cannot get same message
- Interface:
  - Mailbox (`mbox`): temporary holding area for messages
    - » Includes both destination location and queue
  - `Send(message,mbox)`
    - » Send message to remote mailbox identified by `mbox`
  - `Receive(buffer,mbox)`
    - » Wait until `mbox` has message, copy into buffer, and return
    - » If threads sleeping on this mbox, wake up one of them

# Using Messages: Send/Receive behavior

- When should `send(message,mbox)` return?
  - When receiver gets message? (i.e. ack received)
  - When message is safely buffered on destination?
  - Right away, if message is buffered on source node?
- Actually two questions here:
  - When can the sender be sure that receiver actually received the message?
  - When can sender reuse the memory containing message?
- Mailbox provides 1-way communication from T1→T2
  - T1→buffer→T2
  - Very similar to producer/consumer
    - » However, can't tell if sender/receiver is local or not!

# Messaging for Producer-Consumer Style

- Using send/receive for producer-consumer style:

```
Producer:
   int msg1[1000];
   while(1) {
      prepare message;
      send(msg1,mbox);
   }
Consumer:
   int buffer[1000];
   while(1) {
      receive(buffer,mbox);
      process message;
   }
```

Send Message

Receive Message

- No need for producer/consumer to keep track of space in mailbox: handled by send/receive
  - TCP manages the size of buffer on far end
  - Restricts sender to forward only what will fit in buffer

# Messaging for Request/Response communication

- What about two-way communication?
  - Request/Response
    - » Read a file stored on a remote machine
    - » Request a web page from a remote web server
  - Also called: client-server
    - » Client ≡ requester, Server ≡ responder
    - » Server provides "service" (file storage) to the client
- Example: File service

```
Client: (requesting the file)
   char response[1000];

   send("read rutabaga", server_mbox);
   receive(response, client_mbox);

Server: (responding with the file)
   char command[1000], answer[1000];

   receive(command, server_mbox);
   decode command;
   read file into answer;
   send(answer, client_mbox);
```

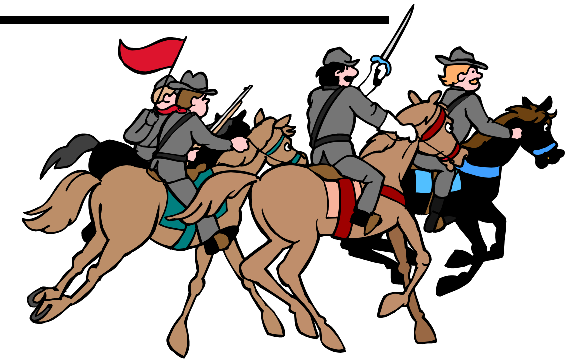
Request File

Get Response

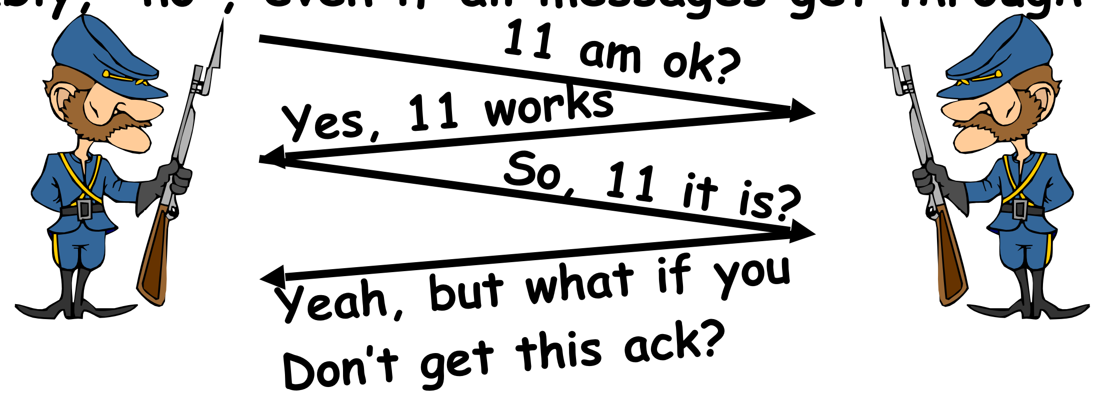
Receive Request

Send Response

# General's Paradox



- General's paradox:
  - Constraints of problem:
    - » Two generals, on separate mountains
    - » Can only communicate via messengers
    - » Messengers can be captured
  - Problem: need to coordinate attack
    - » If they attack at different times, they all die
    - » If they attack at same time, they win
  - Named after Custer, who died at Little Big Horn because he arrived a couple of days too early
- Can messages over an unreliable network be used to guarantee two entities do something simultaneously?
  - Remarkably, "no", even if all messages get through




  - No way to be sure last message gets through!

# Two-Phase Commit

- Since we can't solve the General's Paradox (i.e. simultaneous action), let's solve a related problem
  - Distributed transaction: Two machines agree to do something, or not do it, atomically
- Two-Phase Commit protocol:
  - Persistent stable log on each machine: keep track of whether commit has happened
    - » If a machine crashes, when it wakes up it first checks its log to recover state of world at time of crash
  - Prepare Phase:
    - » The global coordinator requests that all participants will promise to commit or rollback the transaction
    - » Participants record promise in log, then acknowledge
    - » If anyone votes to abort, coordinator writes "`Abort`" in its log and tells everyone to abort; each records "`Abort`" in log
  - Commit Phase:
    - » After all participants respond that they are prepared, then the coordinator writes "`Commit`" to its log
    - » Then asks all nodes to commit; they respond with ack
    - » After receive acks, coordinator writes "`Got Commit`" to log
  - Log can be used to complete this process such that all machines either commit or don't commit

# 2PC Algorithm

- Developed by Turing award winner Jim Gray (first Berkeley CS PhD, 1969)
- One coordinator
- N workers (replicas)
- High level algorithm description
  - Coordinator asks all workers if they can commit
  - If all workers reply "VOTE-COMMIT", then coordinator broadcasts "GLOBAL-COMMIT",

    Otherwise coordinator broadcasts "GLOBAL-ABORT"
  - Workers obey the GLOBAL messages
- Use a persistent, stable log on each machine to keep track of what you are doing
  - If a machine crashes, when it wakes up it first checks its log to recover state of world at time of crash

# Detailed Algorithm

## Coordinator Algorithm

Coordinator sends **VOTE-REQ** to all workers

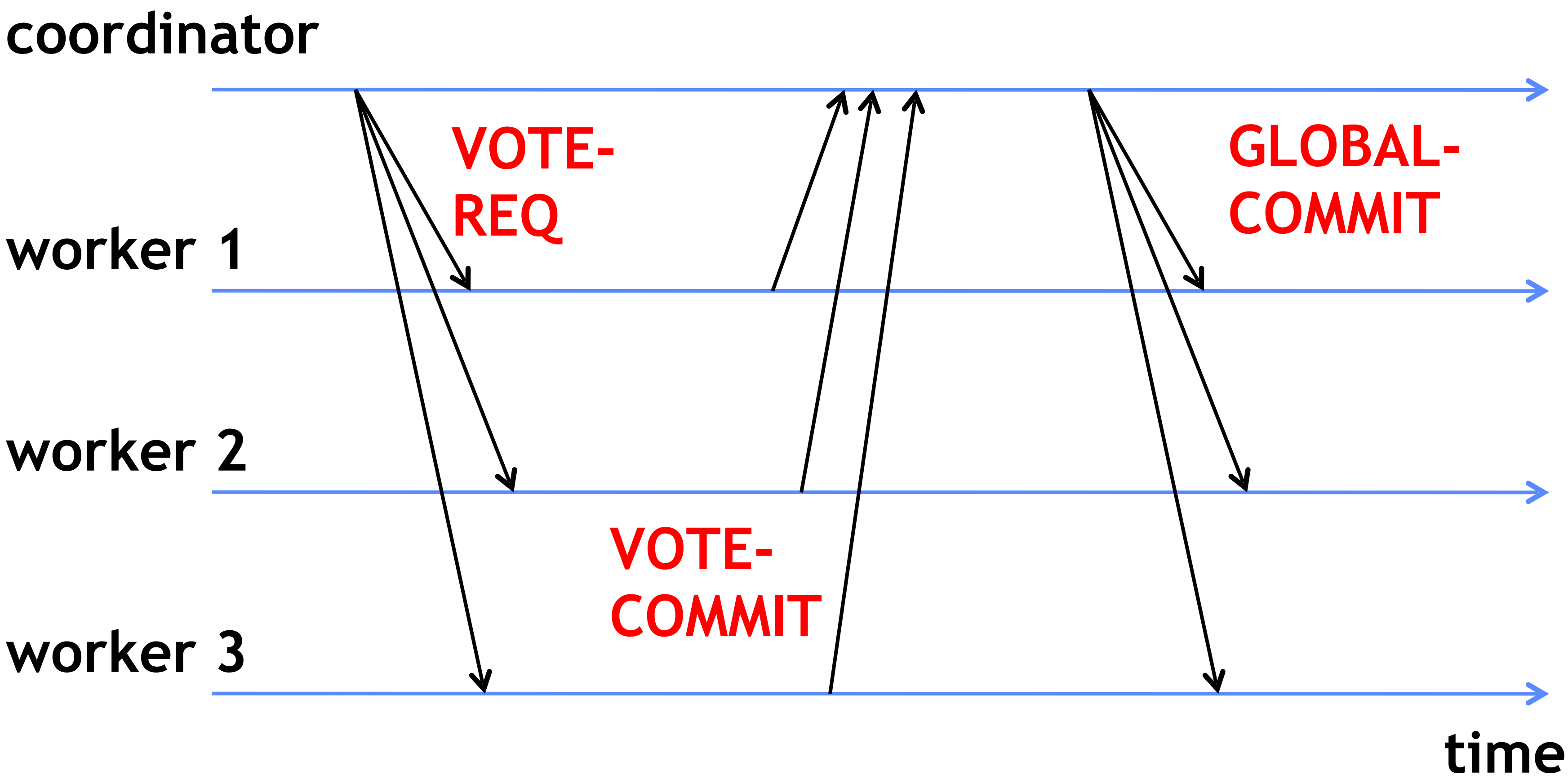
- If receive VOTE-COMMIT from all N workers, send GLOBAL-COMMIT to all workers
- If doesn't receive VOTE-COMMIT from all N workers, send GLOBAL-ABORT to all workers

## Worker Algorithm

- Wait for **VOTE-REQ** from coordinator
- If ready, send **VOTE-COMMIT** to coordinator
- If not ready, send **VOTE-ABORT** to coordinator
  - And immediately abort

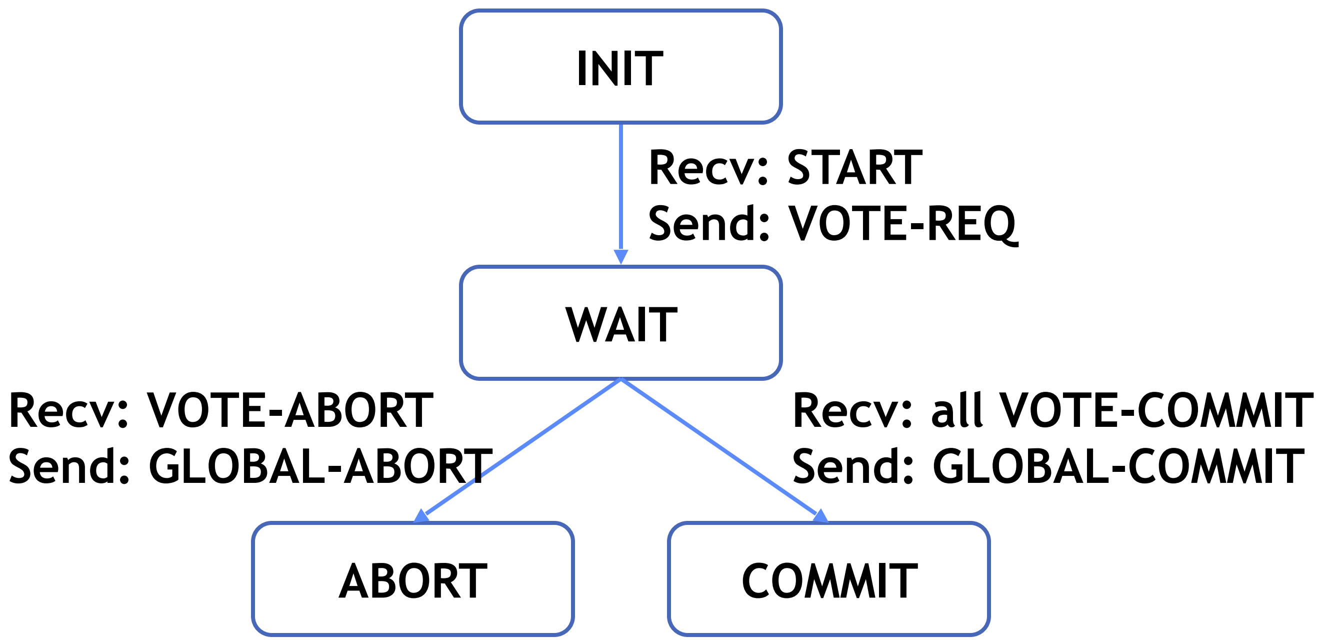
- If receive GLOBAL-COMMIT then commit
- If receive GLOBAL-ABORT then abort

# Failure Free Example Execution

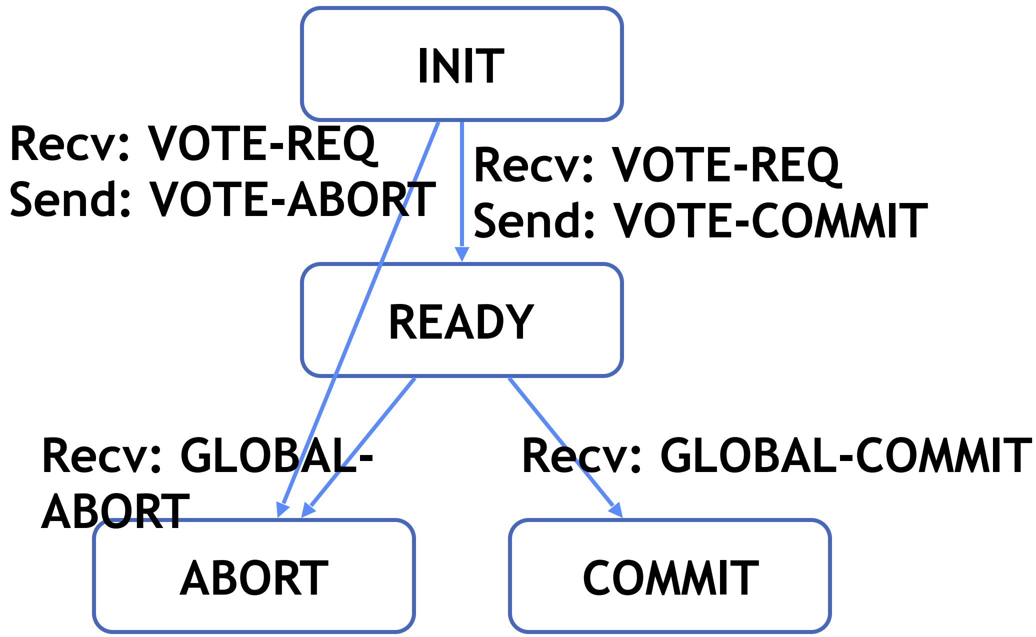


# State Machine of Coordinator

- Coordinator implements simple state machine:

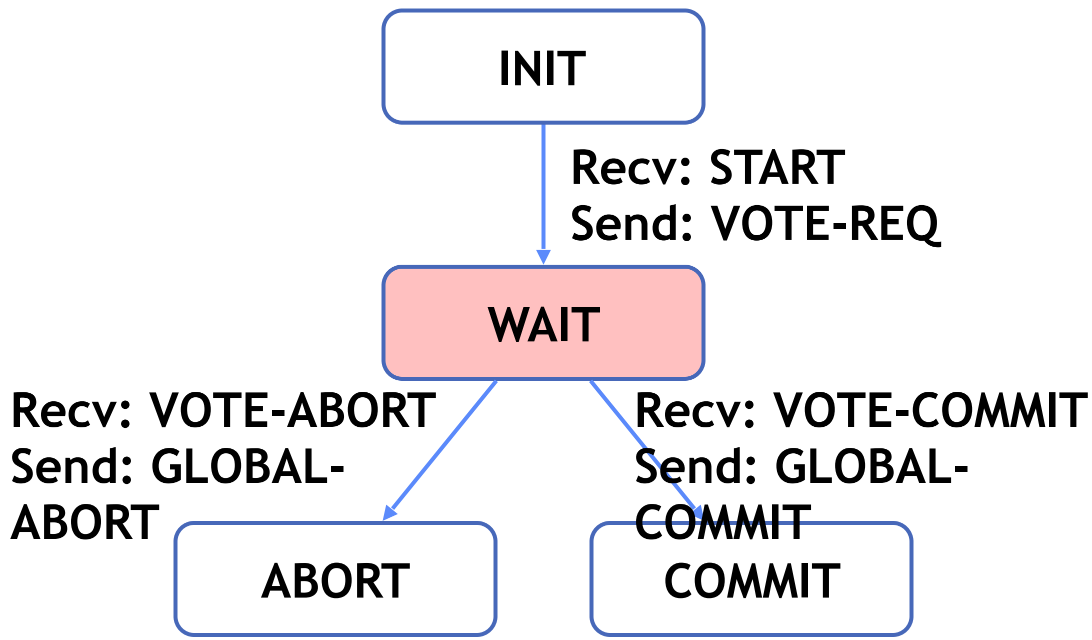


# State Machine of Workers

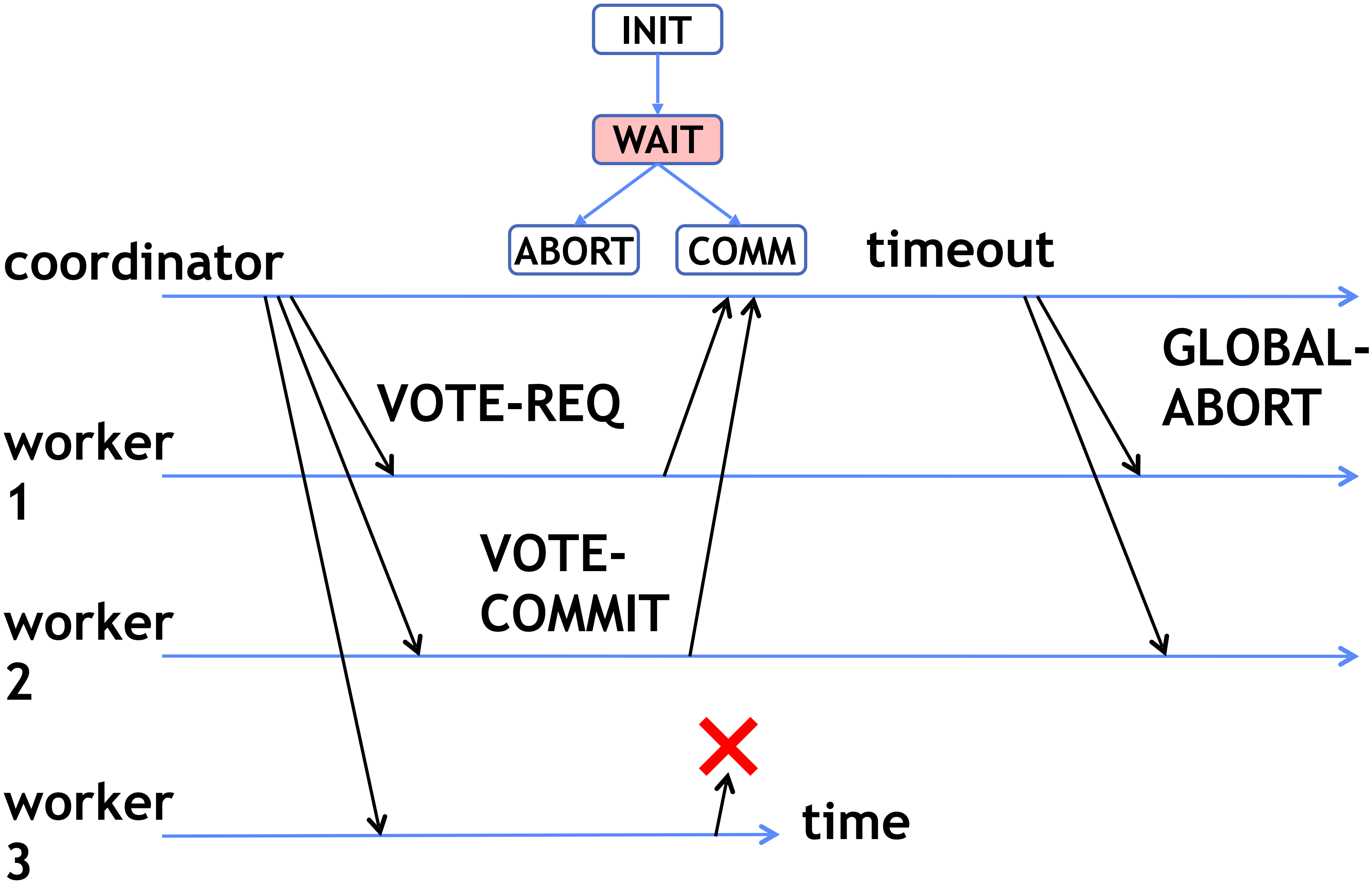


# Dealing with Worker Failures

- How to deal with worker failures?
  - Failure only affects states in which the node is waiting for messages
  - Coordinator only waits for votes in "WAIT" state
  - In WAIT, if doesn't receive
  - N votes, it times out and sends
  - GLOBAL-ABORT

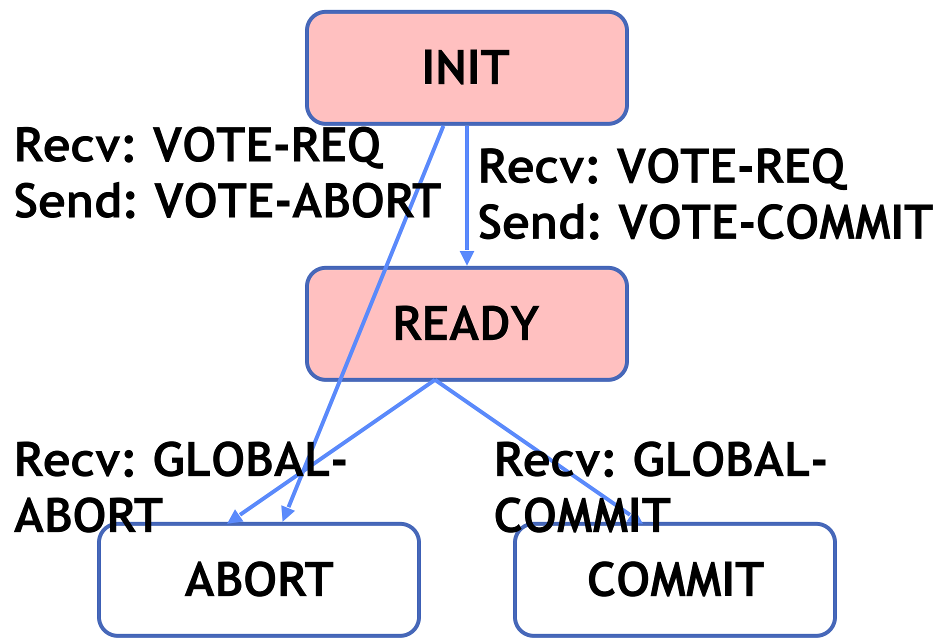


# Example of Worker Failure

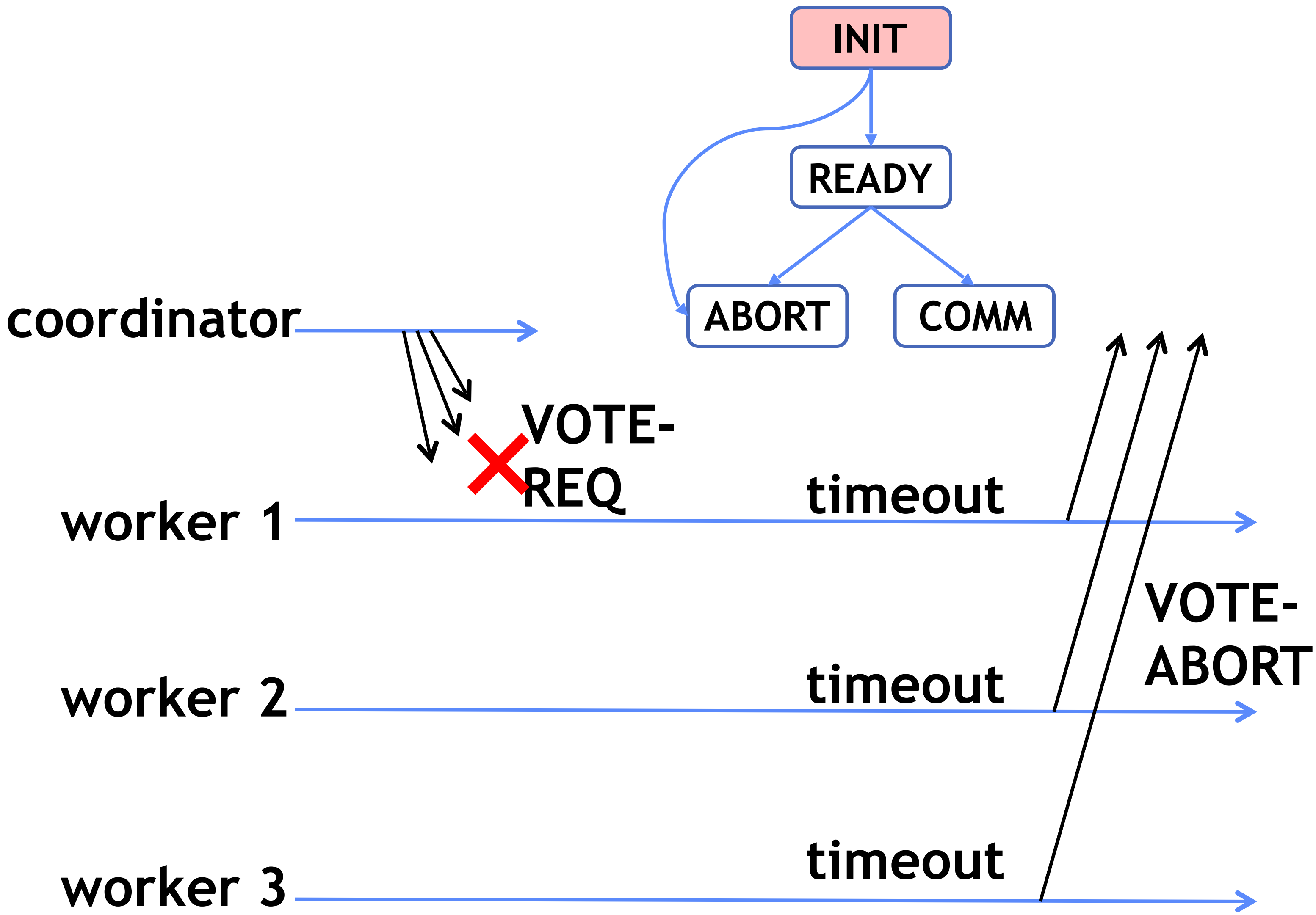


# Dealing with Coordinator Failure

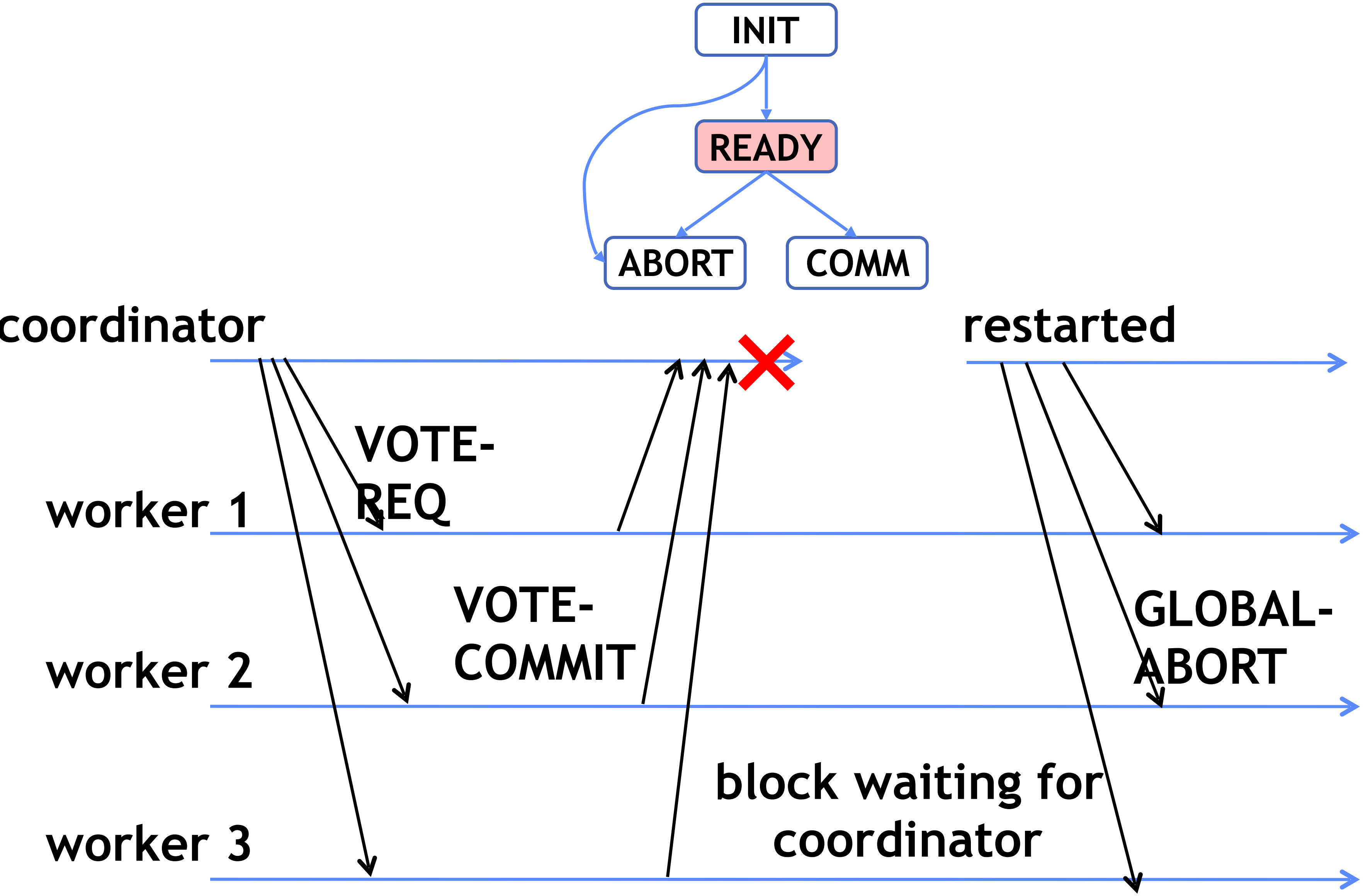
- How to deal with coordinator failures?
  - worker waits for VOTE-REQ in INIT
    - » Worker can time out and abort (coordinator handles it)
  - worker waits for GLOBAL-* message in READY
    - » If coordinator fails, workers must BLOCK waiting for coordinator to recover and send GLOBAL_* message



# Example of Coordinator Failure #1



# Example of Coordinator Failure #2

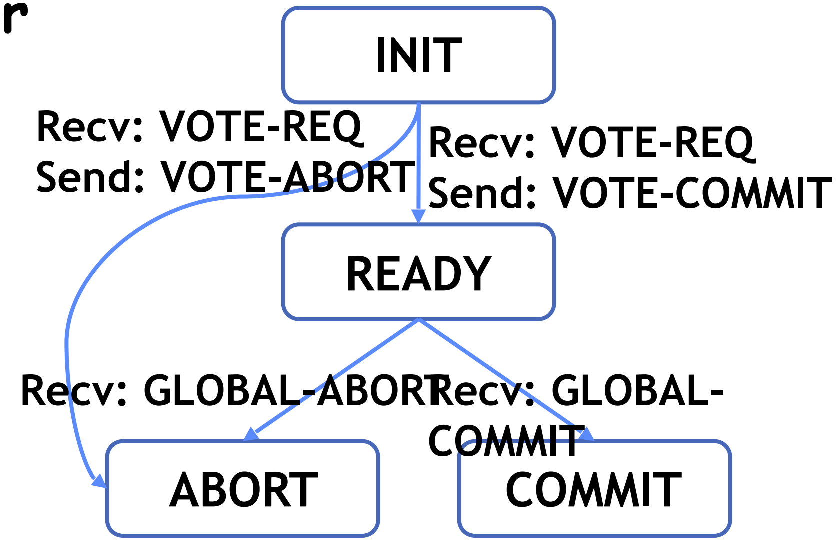


# Durability

- All nodes use stable storage to store current state
  - stable storage is non-volatile storage (e.g. backed by disk) that guarantees atomic writes.
- Upon recovery, it can restore state and resume:
  - Coordinator aborts in INIT, WAIT, or ABORT
  - Coordinator commits in COMMIT
  - Worker aborts in INIT, ABORT
  - Worker commits in COMMIT
  - Worker asks Coordinator in READY

# Blocking for Coordinator to Recover

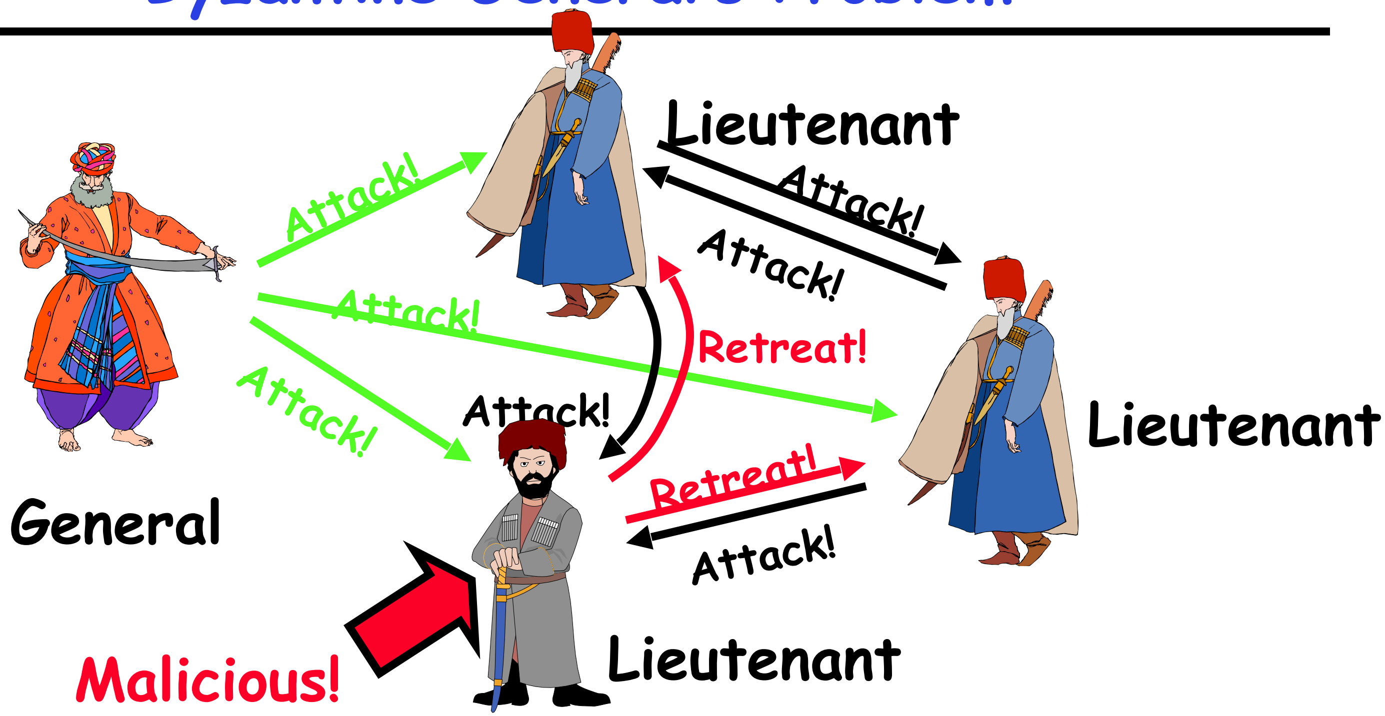
- A worker waiting for global decision can ask fellow workers about their state
  - If another worker is in ABORT or COMMIT state then coordinator must have sent GLOBAL-*
    - » Thus, worker can safely abort or commit, respectively
  - If another worker is still in INIT state then both workers can decide to abort
  - If all workers are in ready, need to BLOCK (don't know if coordinator wanted to abort or commit)



# Distributed Decision Making Discussion

- Why is distributed decision making desirable?
  - Fault Tolerance!
  - A group of machines can come to a decision even if one or more of them fail during the process
  - After decision made, result recorded in multiple places
- Undesirable feature of Two-Phase Commit: Blocking
  - One machine can be stalled until another site recovers:
    - » Site B writes "`prepared to commit`" record to its log, sends a "yes" vote to the coordinator (site A) and crashes
    - » Site A crashes
    - » Site B wakes up, check its log, and realizes that it has voted "yes" on the update. It sends a message to site A asking what happened. At this point, B cannot decide to abort, because update may have committed
    - » B is blocked until A comes back
  - A blocked site holds resources (locks on updated items, pages pinned in memory, etc) until learns fate of update
- PAXOS: An alternative used by GOOGLE and others that does not have this blocking problem
- What happens if one or more of the nodes is malicious?
  - Malicious: attempting to compromise the decision making

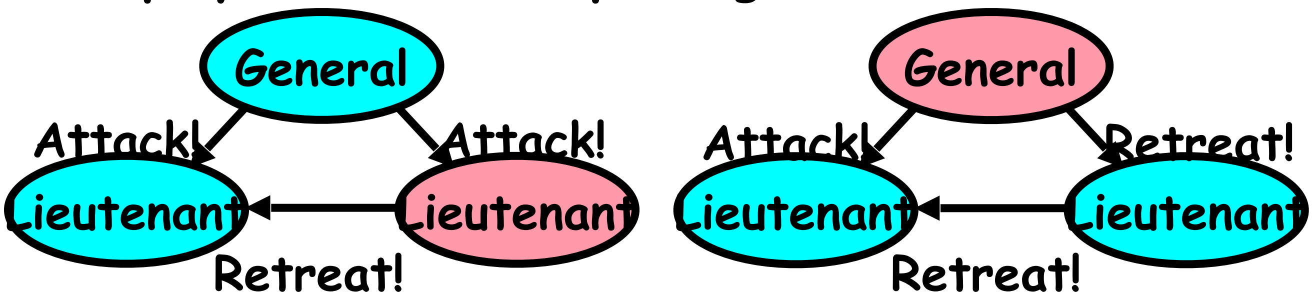
# Byzantine General's Problem



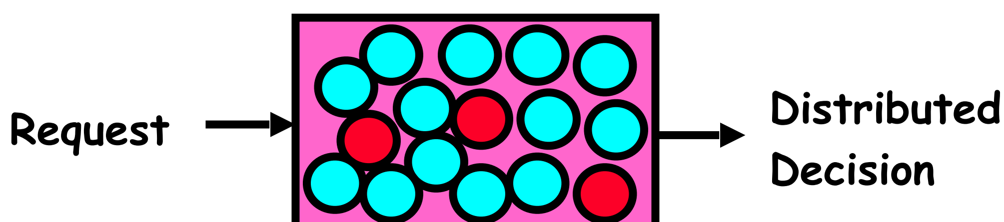

- Byazantine General's Problem (n players):
  - One General
  - n-1 Lieutenants
  - Some number of these (f) can be insane or malicious
- The commanding general must send an order to his n-1 lieutenants such that:
  - All loyal lieutenants obey the same order
  - If the commanding general is loyal, then all loyal lieutenants obey the order he sends

# Byzantine General's Problem (con't)

- Impossibility Results:
  - Cannot solve Byzantine General's Problem with n=3 because one malicious player can mess up things




  - With f faults, need n > 3f to solve problem
- Various algorithms exist to solve problem
  - Original algorithm has #messages exponential in n
  - Newer algorithms have message complexity $O(n^2)$
    - » One from MIT, for instance (Castro and Liskov, 1999)
- Use of BFT (Byzantine Fault Tolerance) algorithm
  - Allow multiple machines to make a coordinated decision even if some subset of them (< n/3 ) are malicious



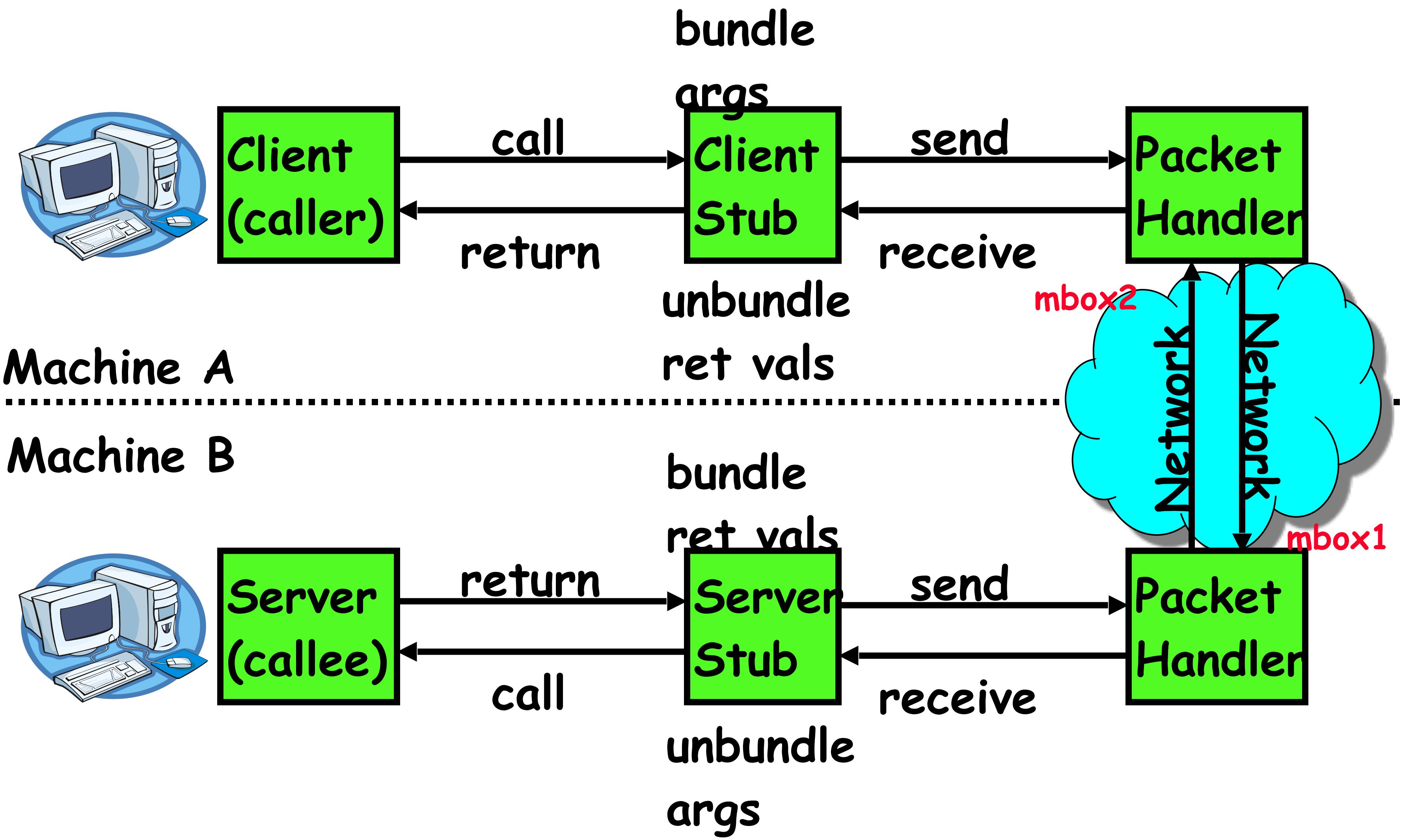
# Remote Procedure Call

- Raw messaging is a bit too low-level for programming
  - Must wrap up information into message at source
  - Must decide what to do with message at destination
  - May need to sit and wait for multiple messages to arrive
- Another option: Remote Procedure Call (RPC)
  - Calls a procedure on a remote machine
  - Client calls:

    ```
    remoteFileSystem→Read("rutabaga");
    ```
  - Translated automatically into call on server:

    ```
    fileSys→Read("rutabaga");
    ```
- Implementation:
  - Request-response message passing (under covers!)
  - "Stub" provides glue on client/server
    - » Client stub is responsible for "marshalling" arguments and "unmarshalling" the return values
    - » Server-side stub is responsible for "unmarshalling" arguments and "marshalling" the return values.
- Marshalling involves (depending on system)
  - Converting values to a canonical form, serializing objects, copying arguments passed by reference, etc.

# RPC Information Flow



# RPC Details

- Equivalence with regular procedure call
  - Parameters ⇔ Request Message
  - Result ⇔ Reply message
  - Name of Procedure: Passed in request message
  - Return Address: mbox2 (client return mail box)
- Stub generator: Compiler that generates stubs
  - Input: interface definitions in an "interface definition language (IDL)"
    - » Contains, among other things, types of arguments/return
  - Output: stub code in the appropriate source language
    - » Code for client to pack message, send it off, wait for result, unpack result and return to caller
    - » Code for server to unpack message, call procedure, pack results, send them off
- Cross-platform issues:
  - What if client/server machines are different architectures or in different languages?
    - » Convert everything to/from some canonical form
    - » Tag every item with an indication of how it is encoded (avoids unnecessary conversions).

# RPC Details (continued)

- How does client know which mbox to send to?
  - Need to translate name of remote service into network endpoint (Remote machine, port, possibly other info)
  - Binding: the process of converting a user-visible name into a network endpoint
    - » This is another word for "naming" at network level
    - » Static: fixed at compile time
    - » Dynamic: performed at runtime
- Dynamic Binding
  - Most RPC systems use dynamic binding via name service
    - » Name service provides dynamic translation of service→mbox
  - Why dynamic binding?
    - » Access control: check who is permitted to access service
    - » Fail-over: If server fails, use a different one
- What if there are multiple servers?
  - Could give flexibility at binding time
    - » Choose unloaded server for each new client
  - Could provide same mbox (router level redirect)
    - » Choose unloaded server for each new request
    - » Only works if no state carried from one call to next
- What if multiple clients?
  - Pass pointer to client-specific return mbox in request

# Problems with RPC

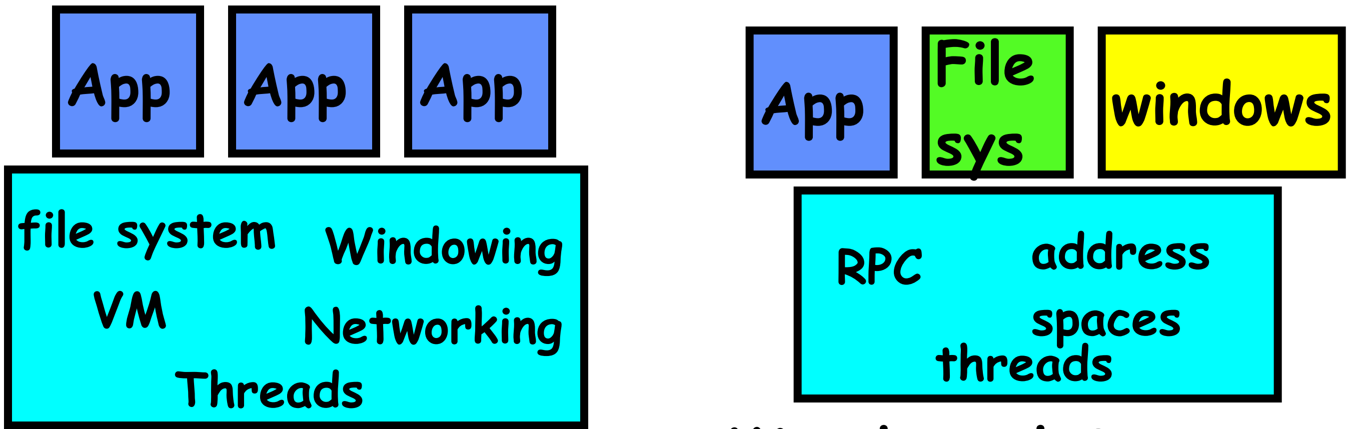
- Non-Atomic failures
  - Different failure modes in distributed system than on a single machine
  - Consider many different types of failures
    - » User-level bug causes address space to crash
    - » Machine failure, kernel bug causes all processes on same machine to fail
    - » Some machine is compromised by malicious party
  - Before RPC: whole system would crash/die
  - After RPC: One machine crashes/compromised while others keep working
  - Can easily result in inconsistent view of the world
    - » Did my cached data get written back or not?
    - » Did server do what I requested or not?
  - Answer? Distributed transactions/Byzantine Commit
- Performance
  - Cost of Procedure call « same-machine RPC « network RPC
  - Means programmers must be aware that RPC is not free
    - » Caching can help, but may make failure handling complex

# Cross-Domain Communication/Location Transparency

- How do address spaces communicate with one another?
  - Shared Memory with Semaphores, monitors, etc…
  - File System
  - Pipes (1-way communication)
  - "Remote" procedure call (2-way communication)
- RPC's can be used to communicate between address spaces on different machines or the same machine
  - Services can be run wherever it's most appropriate
  - Access to local and remote services looks the same
- Examples of modern RPC systems:
  - CORBA (Common Object Request Broker Architecture)
  - DCOM (Distributed COM)
  - RMI (Java Remote Method Invocation)

# Microkernel operating systems

- Example: split kernel into application-level servers.
  - File system looks remote, even though on same machine




Monolithic Structure

Microkernel Structure

- Why split the OS into separate domains?
  - Fault isolation: bugs are more isolated (build a firewall)
  - Enforces modularity: allows incremental upgrades of pieces of software (client or server)
  - Location transparent: service can be local or remote
    - » For example in the X windowing system: Each X client can be on a separate machine from X server; Neither has to run on the machine with the frame buffer.

# Summary

- Protocol: Agreement between two parties as to how information is to be transmitted
- Two-phase commit: distributed decision making
  - First, make sure everyone guarantees that they will commit if asked (prepare)
  - Next, ask everyone to commit
- Byzantine General's Problem: distributed decision making with malicious failures
  - One general, n-1 lieutenants: some number of them may be malicious (often "f" of them)
  - All non-malicious lieutenants must come to same decision
  - If general not malicious, lieutenants must follow general
  - Only solvable if $n \geq 3f+1$
- Remote Procedure Call (RPC): Call procedure on remote machine
  - Provides same interface as procedure
  - Automatic packing and unpacking of arguments without user programming (in stub)